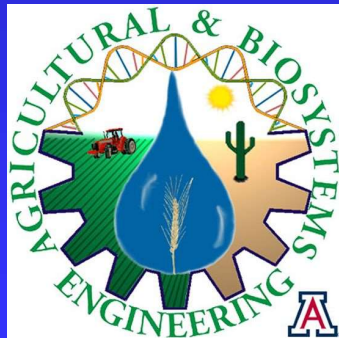
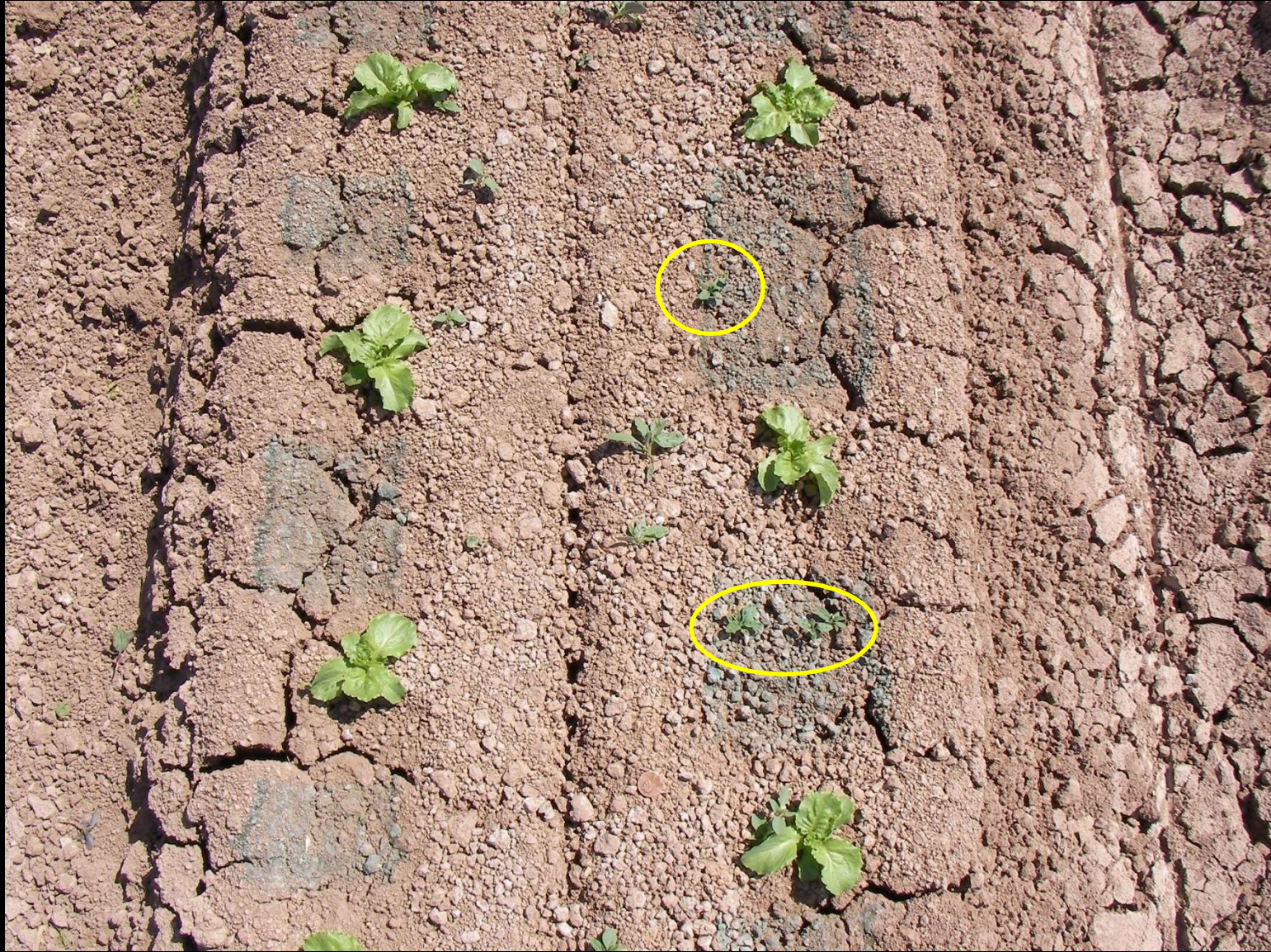


Engineering Concerns for Mechanized In-Row Weed Control

Mark C. Siemens
University of Arizona
Department of Ag and Biosystems Engineering



2016 Salinas Valley Weed School, November 2, 2016



In-Row Weeds

In-Row Weeders

- Commercialized – 2008
- Developed in Europe
 - High labor costs
- Latest technologies
 - U.S. market - 2014



Stekettee IC

Distributor – Sutton Ag Enterprises, Inc., Salinas, CA



Stekettee IC

Distributor – Sutton Ag Enterprises, Inc., Salinas, CA



Robovator

F. Poulsen Engineering ApS

Distributors – KULT-Kress, New Holland, PA and Pacific Ag Rentals, LLC, Salinas, CA



Robovator

F. Poulsen Engineering ApS

Distributors – KULT-Kress, New Holland, PA and Pacific Ag Rentals, LLC, Salinas, CA



Standard Cultivator



Robovator

Weed Control Effectiveness

Cult Herb ^b	Weed Density ^a									
	Exp. 1		Exp. 2		Exp. 3		Exp. 4		Exp. 5	
	-----no. ft ⁻² -----									
	Pre	Post	Pre	Post	Pre	Post	Pre	Post	Pre	Post
Conv w/o	45.0 a	15.0 a	12.8 a	3.5 a	1.0 a	0.3 a	31.0 a	15.5 a	12.2 a	3.5 a
Robo w/o	40.0 a	4.8 b	15.7 a	1.3 b	1.3 a	0.2 ab	37.6 a	5.9 b	10.0 a	1.2 b
Conv with	5.0 b	0.7 b	5.4 b	0.9 b	0.0 b	0.0 b	9.7 b	3.4 b	0.7 b	0.1 c
Robo with	6.3 b	0.4 b	6.9 b	0.2 b	0.0 b	0.0 b	6.9 b	0.5 b	0.9 b	0.3 c

^a Means with the same letter within columns are not significantly different according to Tukey-Kramer Honestly Significant Difference (HSD) test P = 0.05.

^bHerbicide for experiments 1 and 5 was pronamide at 1.2 lb ai ac⁻¹ (\$60 ac⁻¹); herbicide for experiments 2, 3 and 4 was DCPA at 7.5 lb ai ac⁻¹ (\$132 ac⁻¹).

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Pre-Cultivation



Post – In-Row Cultivation

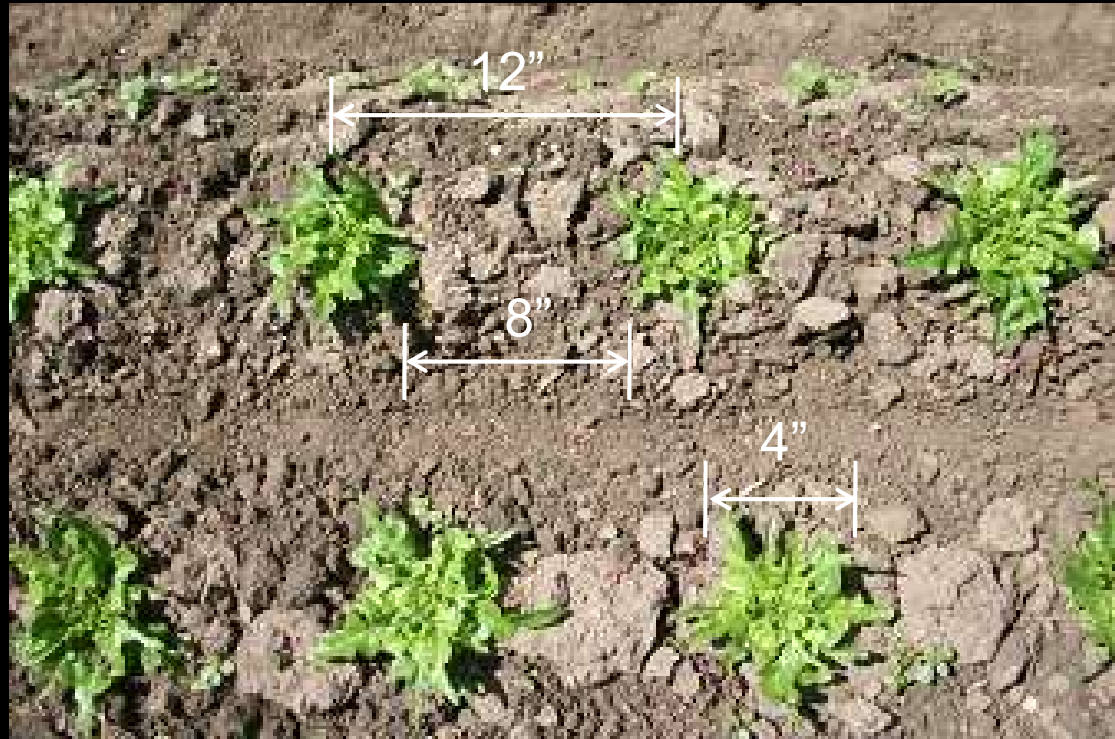
Weed Control Effectiveness

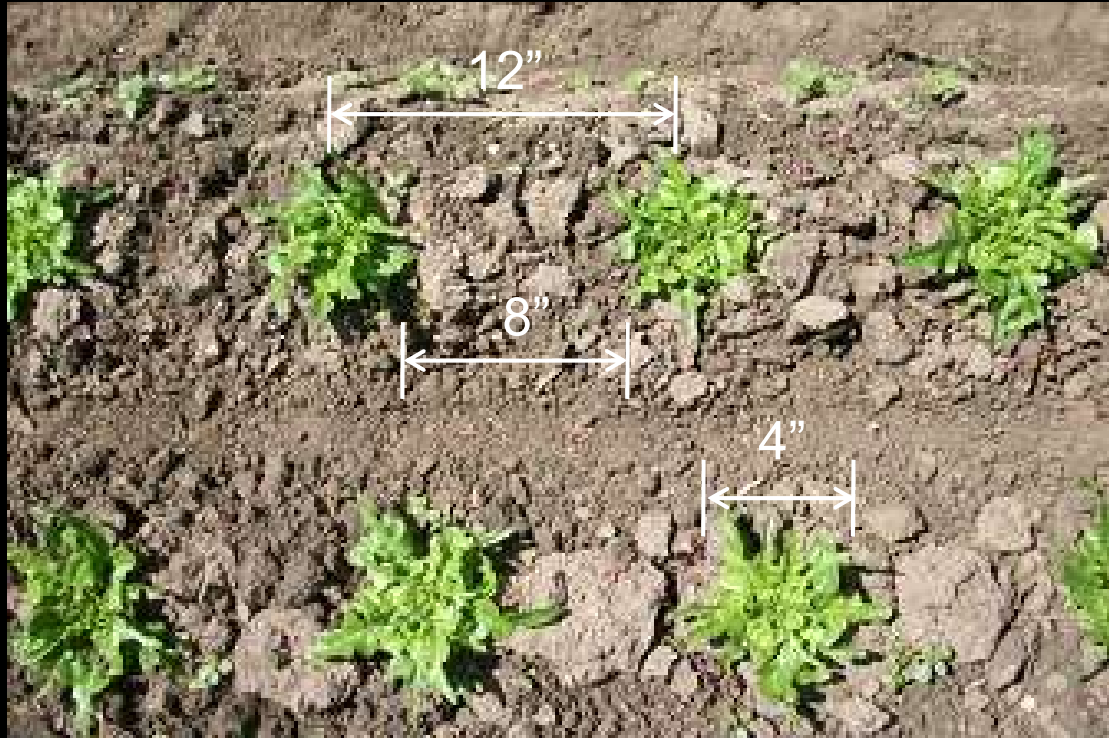
~ 2/3rds In-Row Weeds

Cult Herb ^b	Weed Density ^a									
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	no. ft ⁻²									
	Pre	Post	Pre	Post	Pre	Post	Pre	Post	Pre	Post
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Conv with	5.0 b	0.7 b	5.4 b	0.9 b	0.0 b	0.0 b	9.7 b	3.4 b	0.7 b	0.1 c
Robo with	6.3 b	0.4 b	6.9 b	0.2 b	0.0 b	0.0 b	6.9 b	0.5 b	0.9 b	0.3 c

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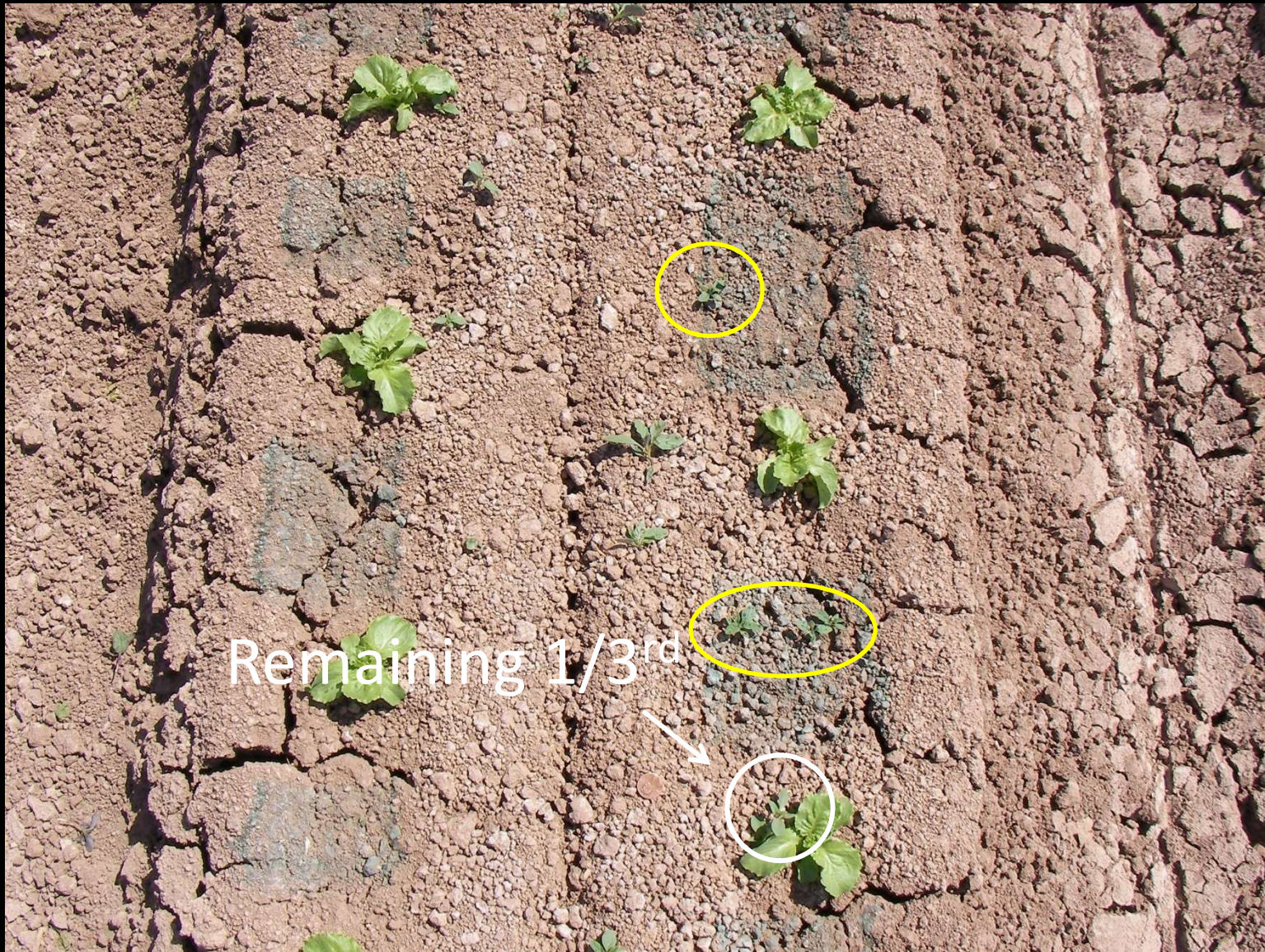




$$\frac{8''}{12''} = \frac{2}{3} \text{ rds}$$



Precision Weeding



Remaining 1/3rd

Precision Weeding

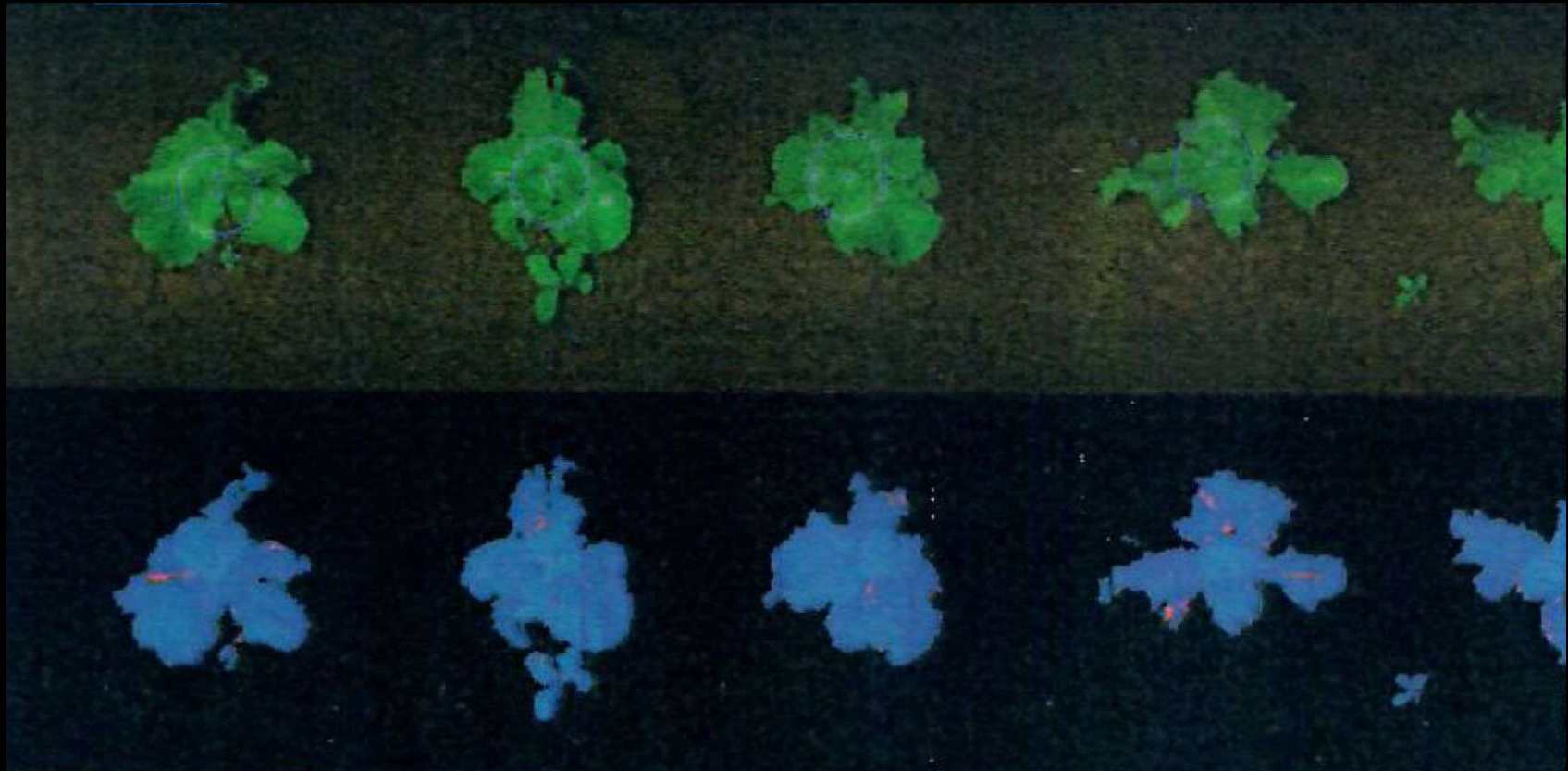
Crop or Weed?



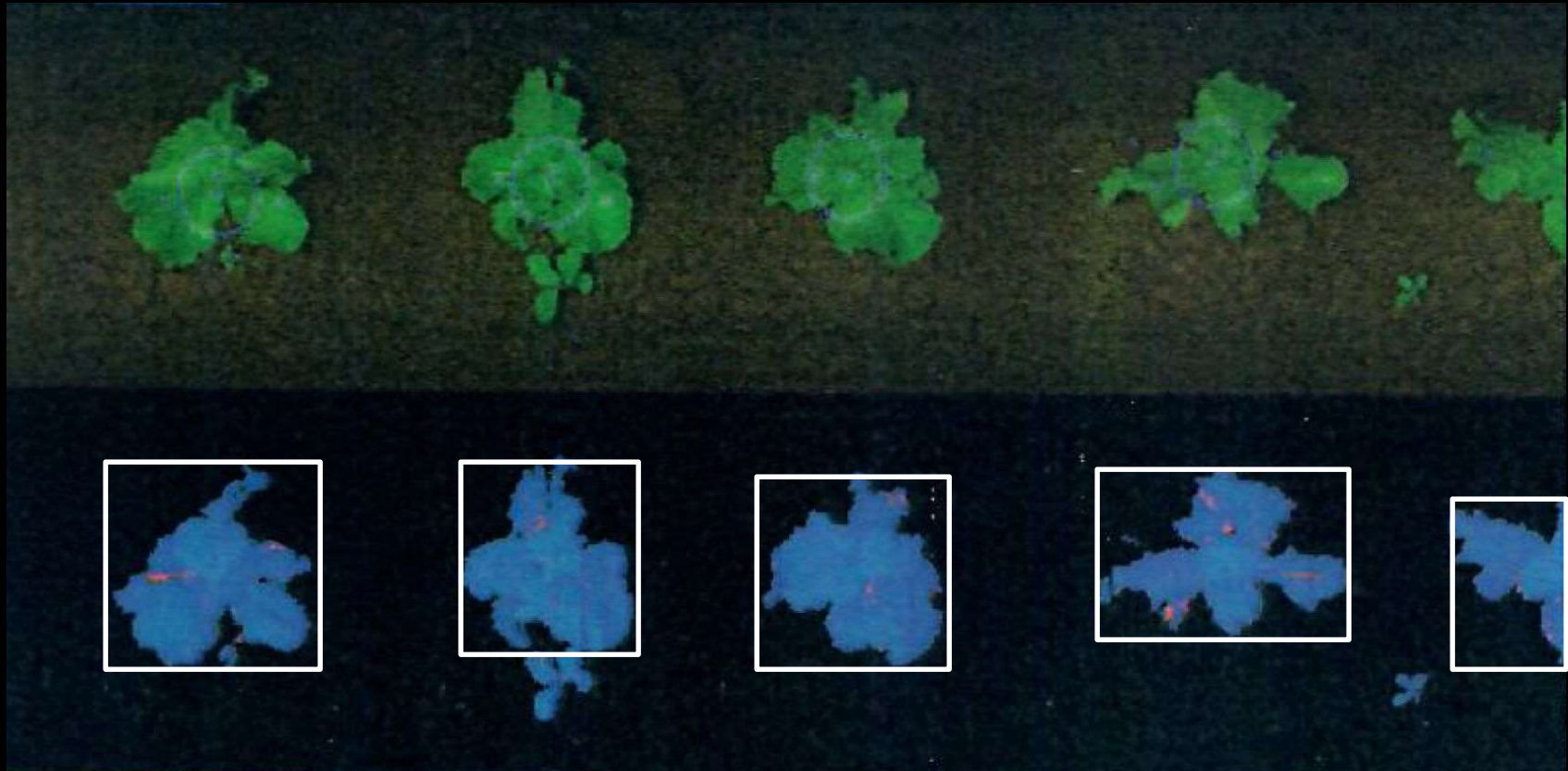
Precision Weeding



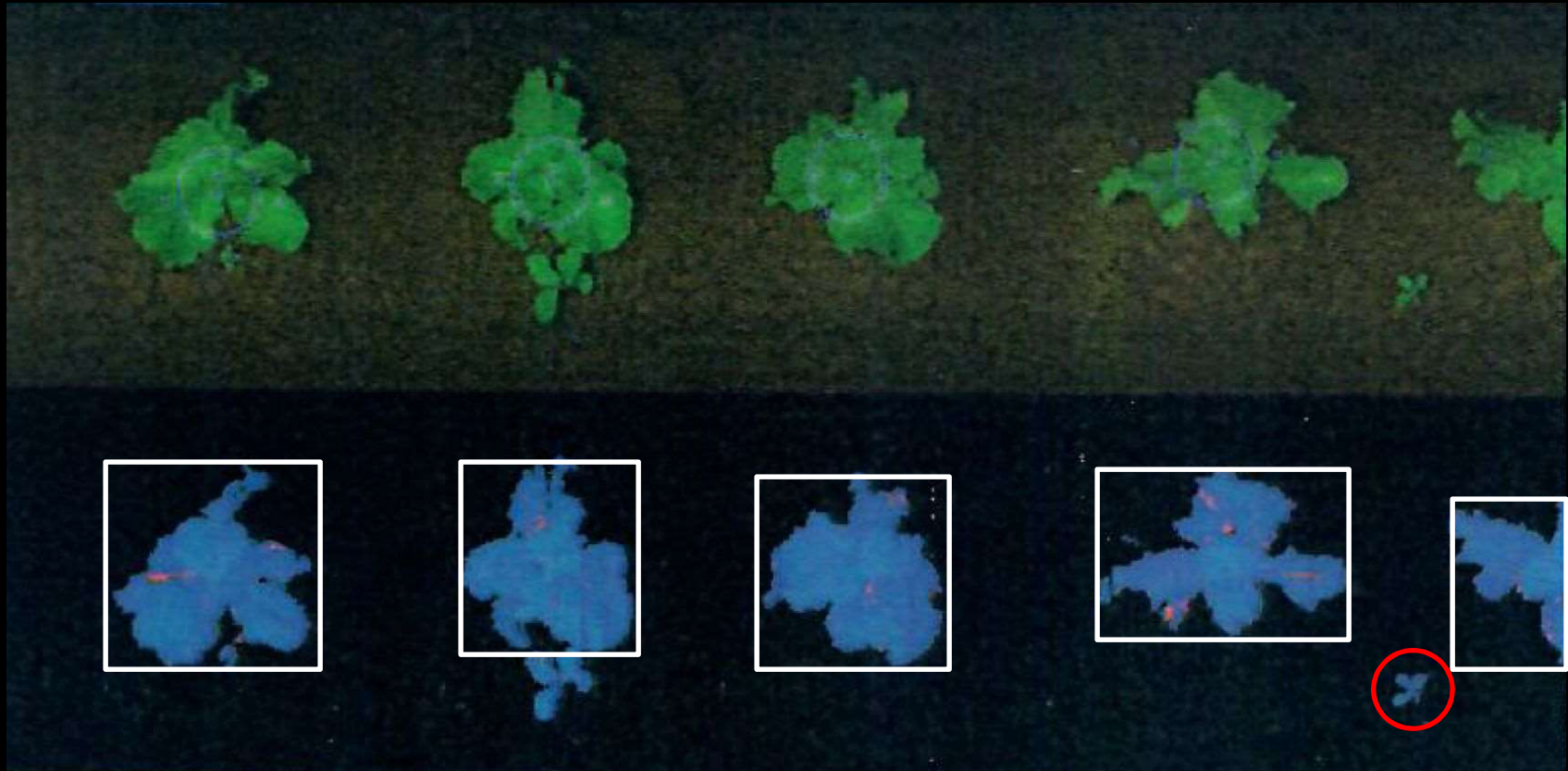
Crop/Weed Classification - Size and Location



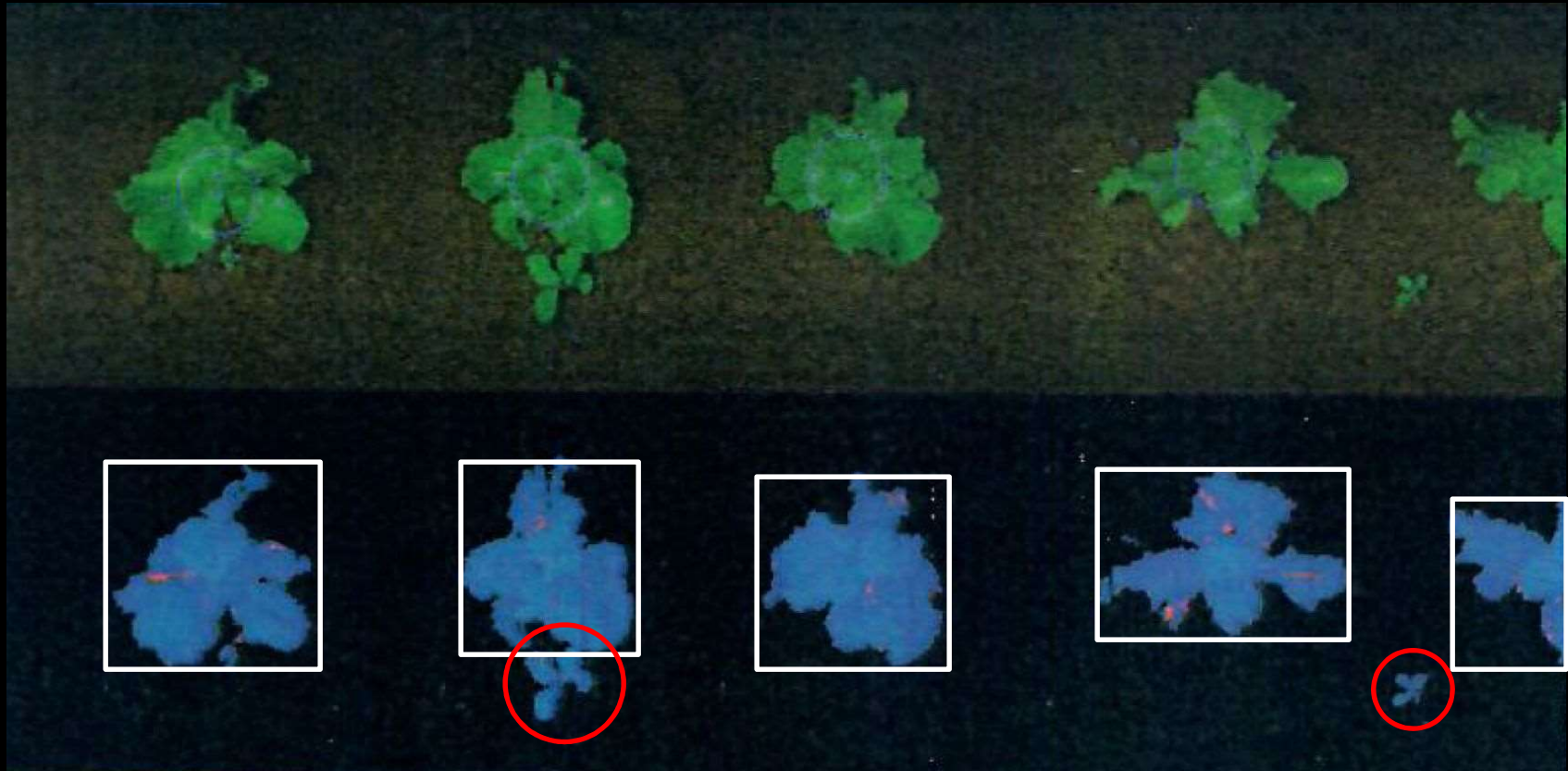
Crop/Weed Classification - Size and Location



Crop/Weed Classification - Size and Location



Crop/Weed Classification - Size and Location



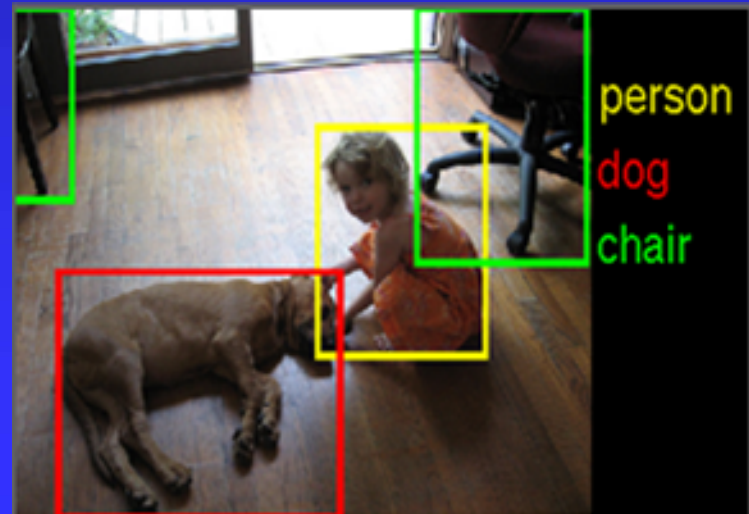
Crop/Weed Classification - Size and Location



Large, Close Weed

Deep Learning

- Training set – numerous images
- Convolutional neural network
- Develops classification scheme
- ImageNet contest - $<1\%$ error



Deep Learning

- Blue River Technologies Inc.
- + \$17 million (December, 2015)
- Spray based precision weeder
- Crops – Cotton, lettuce, others





BLUERIVER
TECHNOLOGIES

Deep Learning - Crop/Weed Classification

Results:

- 90-95% detection rates
- 1,000 image training set



BLUE RIVER
TECHNOLOGIES

Deep Learning - Crop/Weed Classification

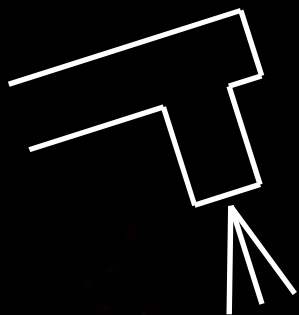


Spray Transplants with Florescent Dye



Spray Transplants with Florescent Dye

Specialty Crop Research Initiative Funded Project



Spray Transplants with Florescent Dye

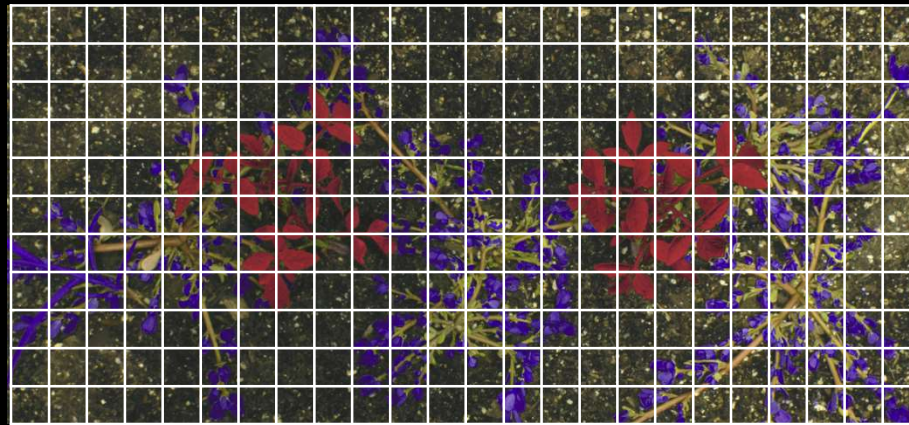
Specialty Crop Research Initiative Funded Project

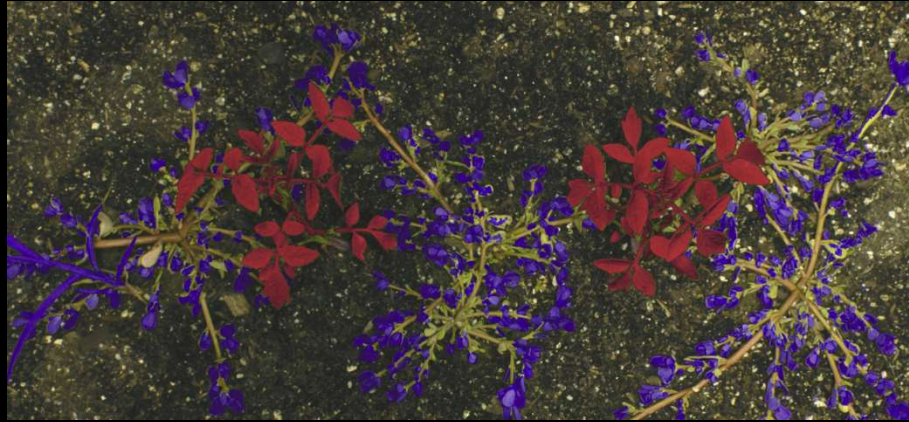


Spray Transplants with Florescent Dye

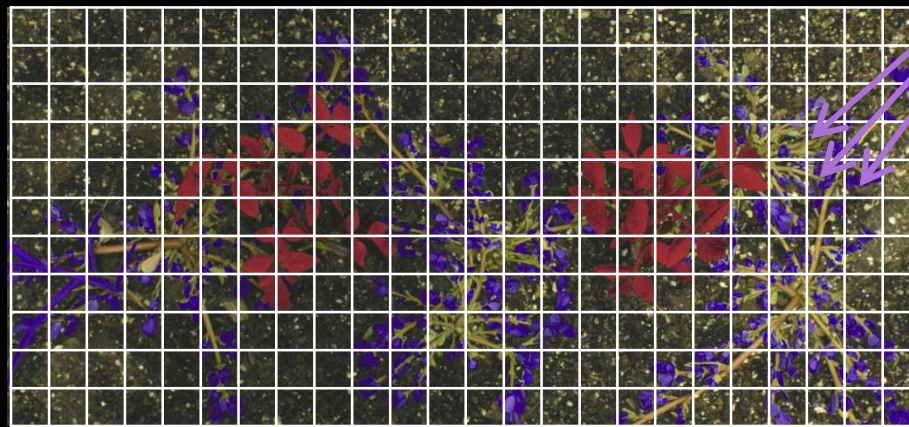
Specialty Crop Research Initiative Funded Project

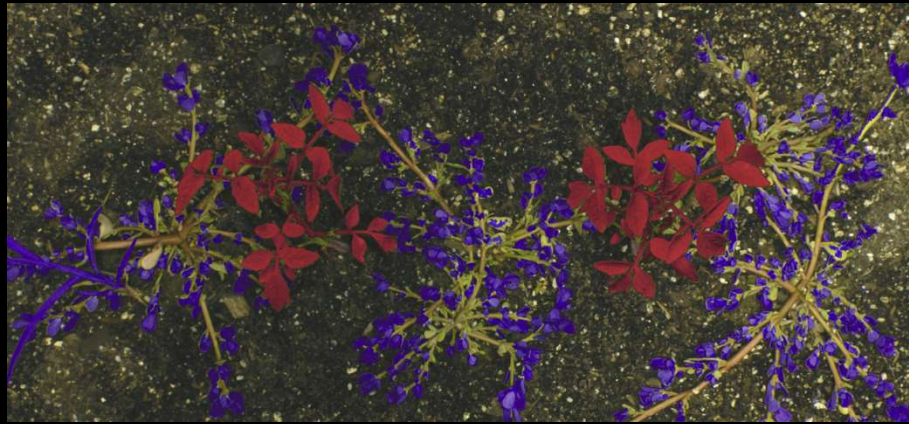




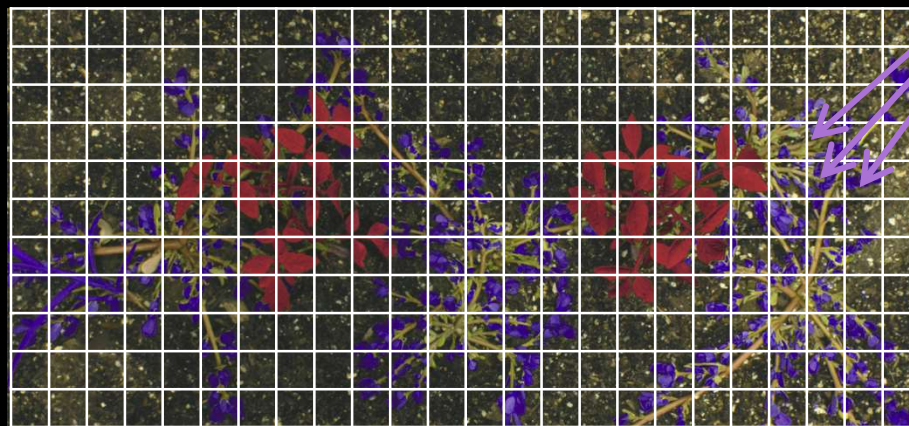


Spray
Zone





Spray
Zone



1 cm

Precision Spray System

- Design Criteria
 - Deliver herbicides at 1-cm level scale accuracy
 - Travel at commercially viable speeds (2 mph)
 - Economically feasible
 - Suitable for use in agricultural environment

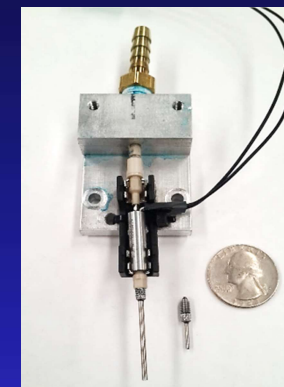
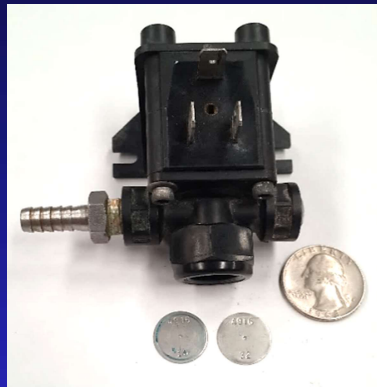
Solenoid Valve/Nozzle Assemblies

Agriculture

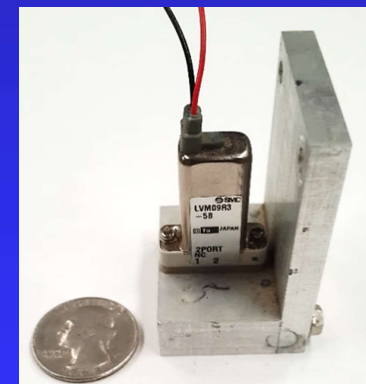
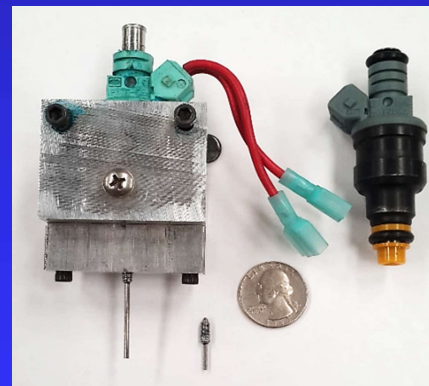
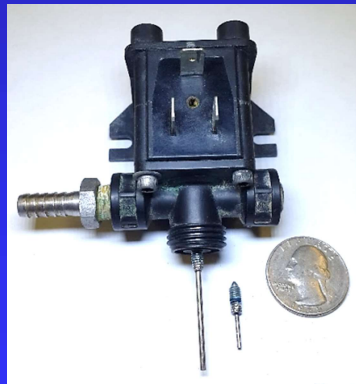
Automotive

Medical

Standard



Custom



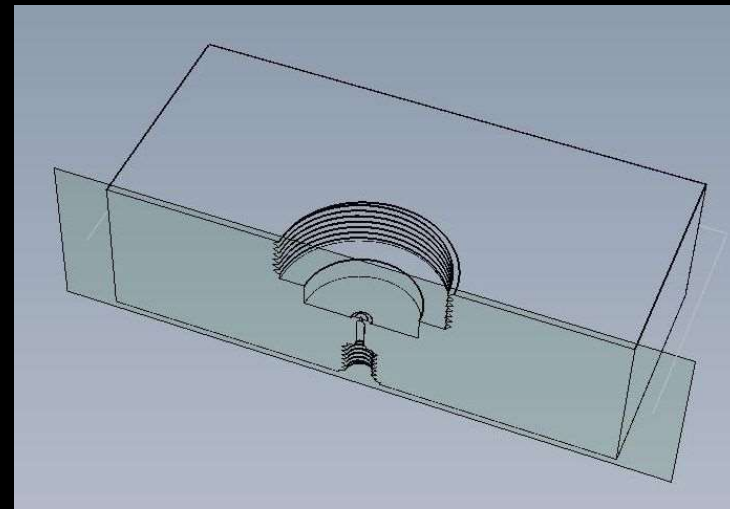
> 40 Solenoid Valve/Nozzle Body Combinations Tested

Feasible Solenoid Valve/Nozzle Body



ODE Valve

- \$30
- Cycle speed (3-4 ms)
- 24 VDC



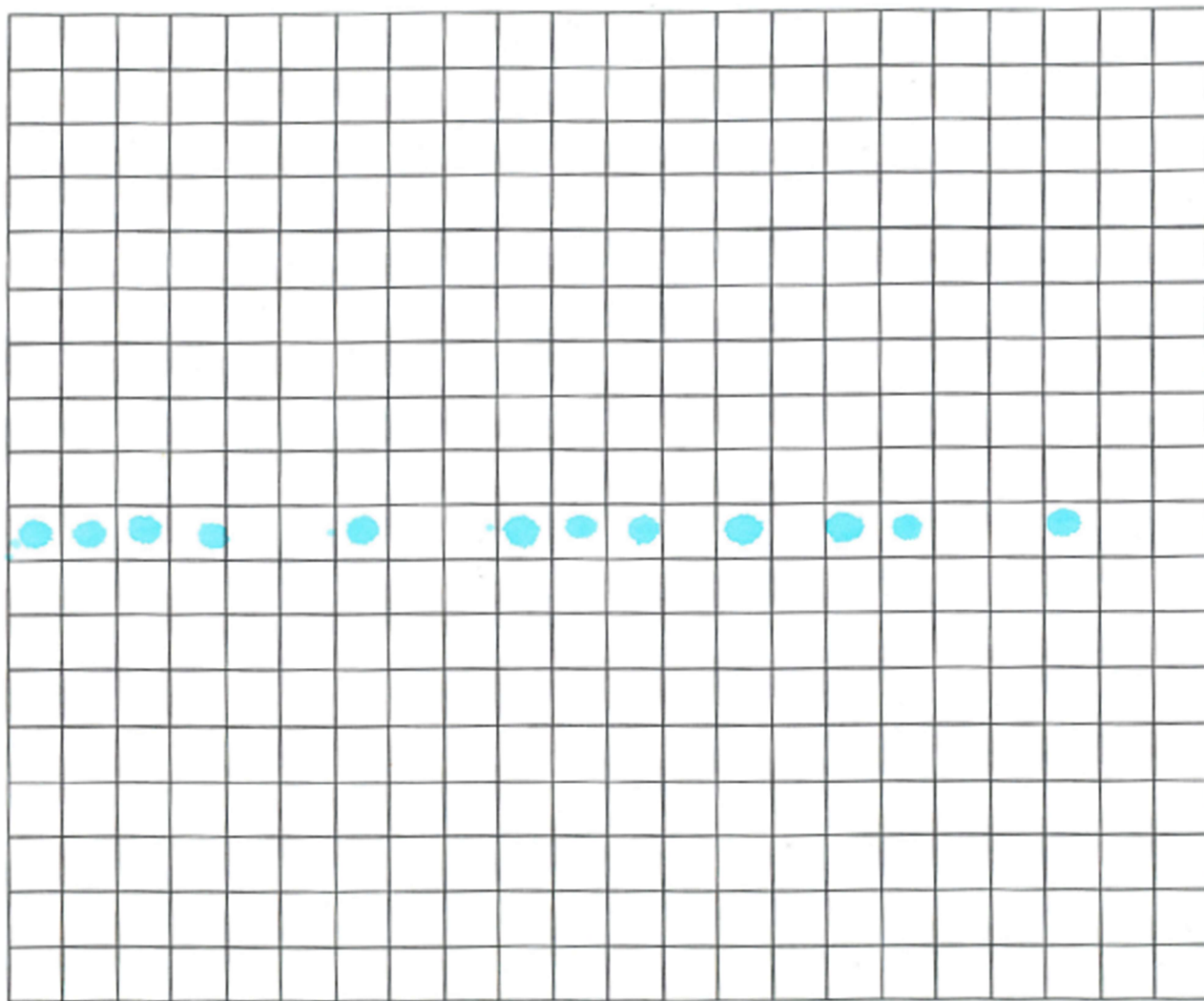
Custom Valve Body

- Patterned after micro-dispensing valve designs



1 cm² "Weed Targets" - 2 mph

1-CENTIMETER GRID PAPER

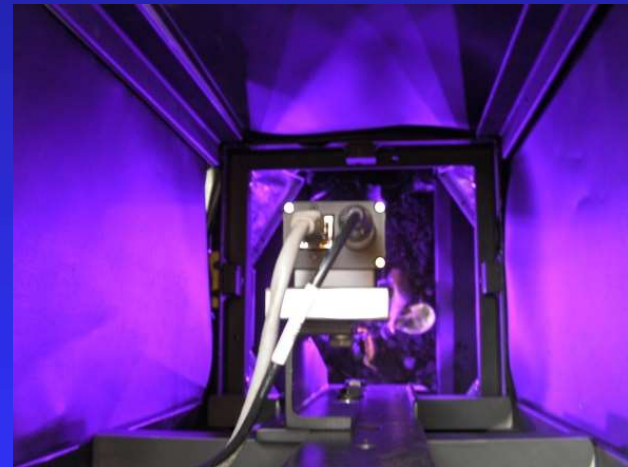
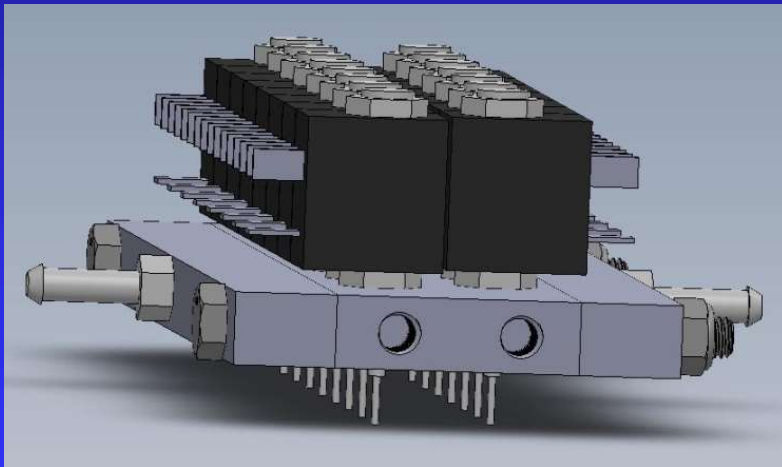


Copyright 2003-2016 www.hanstrom.com

1 cm² "Weed Targets" - 2 mphc

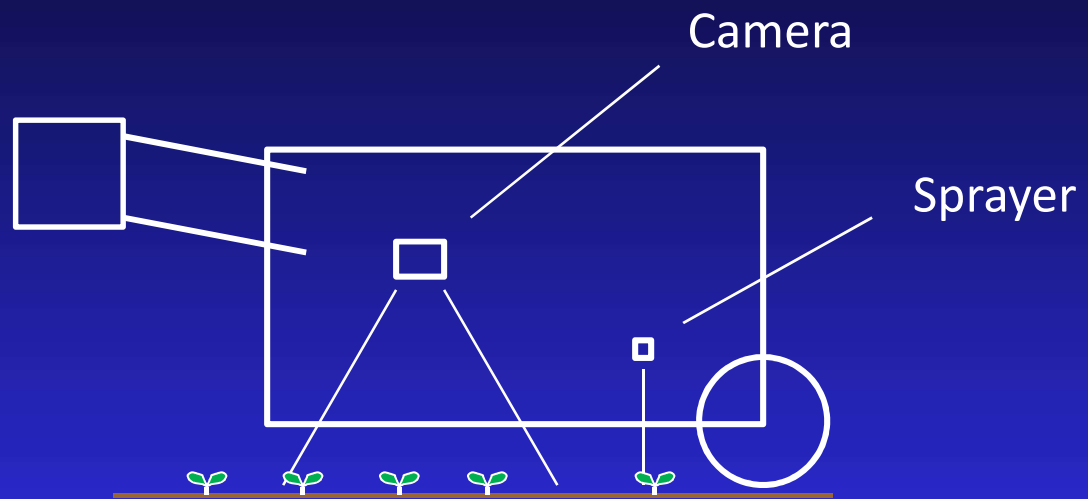
Future Work

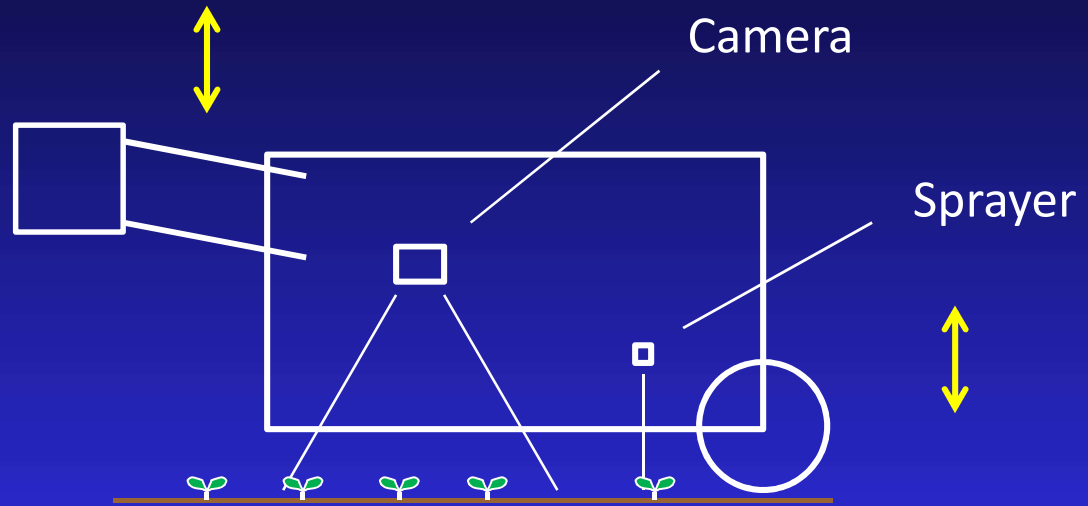
- Integrate Spray and Visions Systems
- Field test

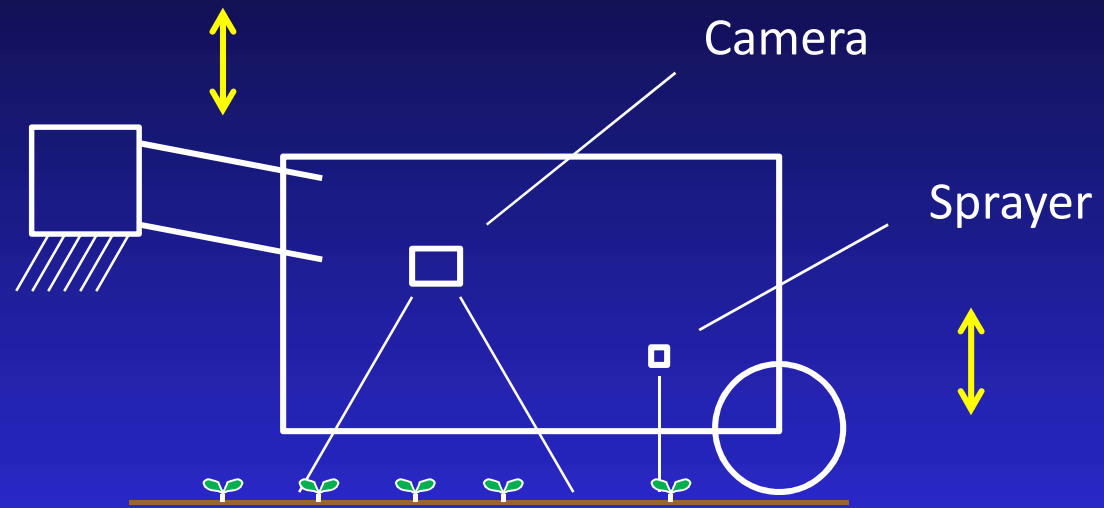


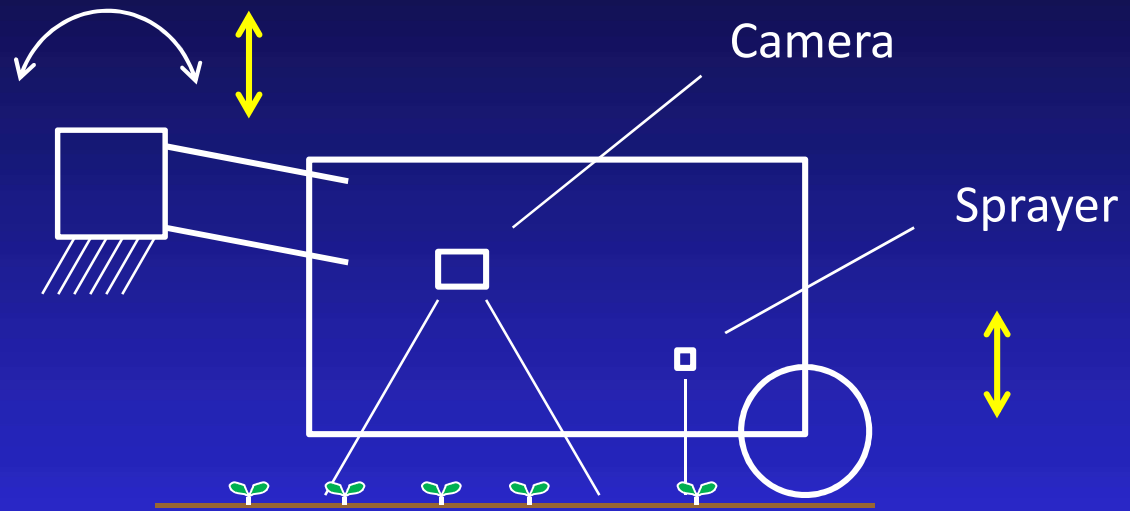


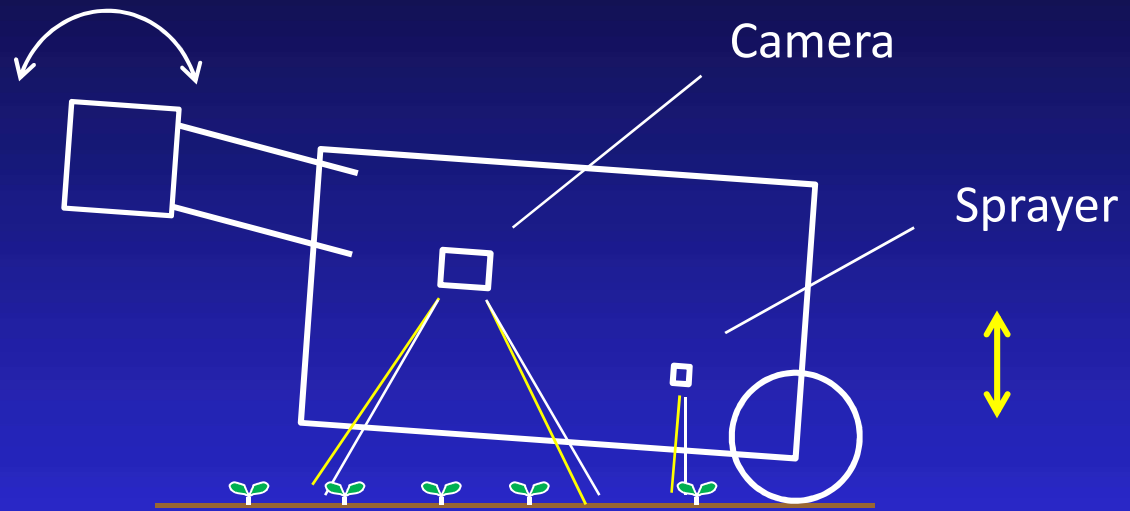
Accuracy - 1/4" ?

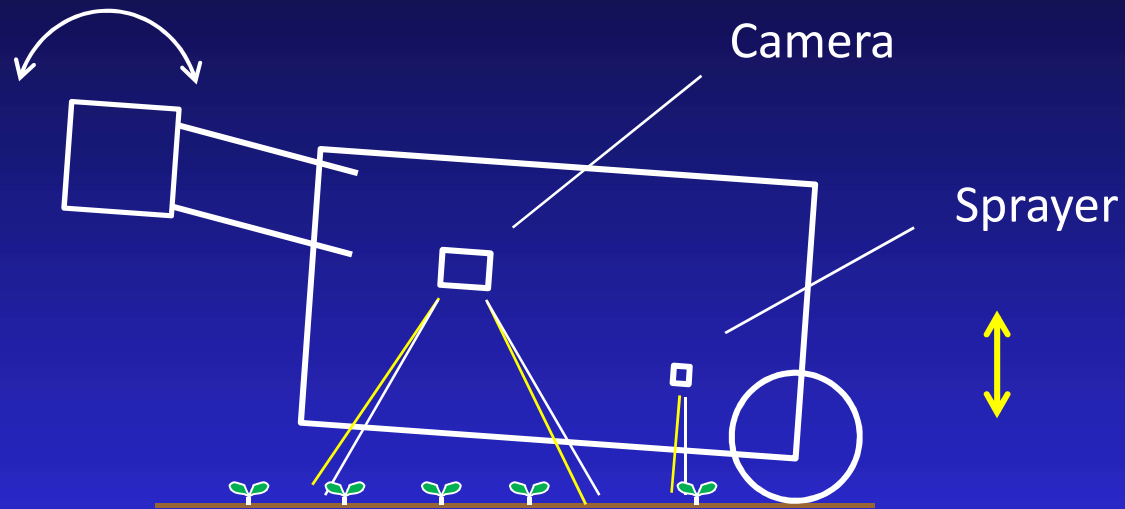










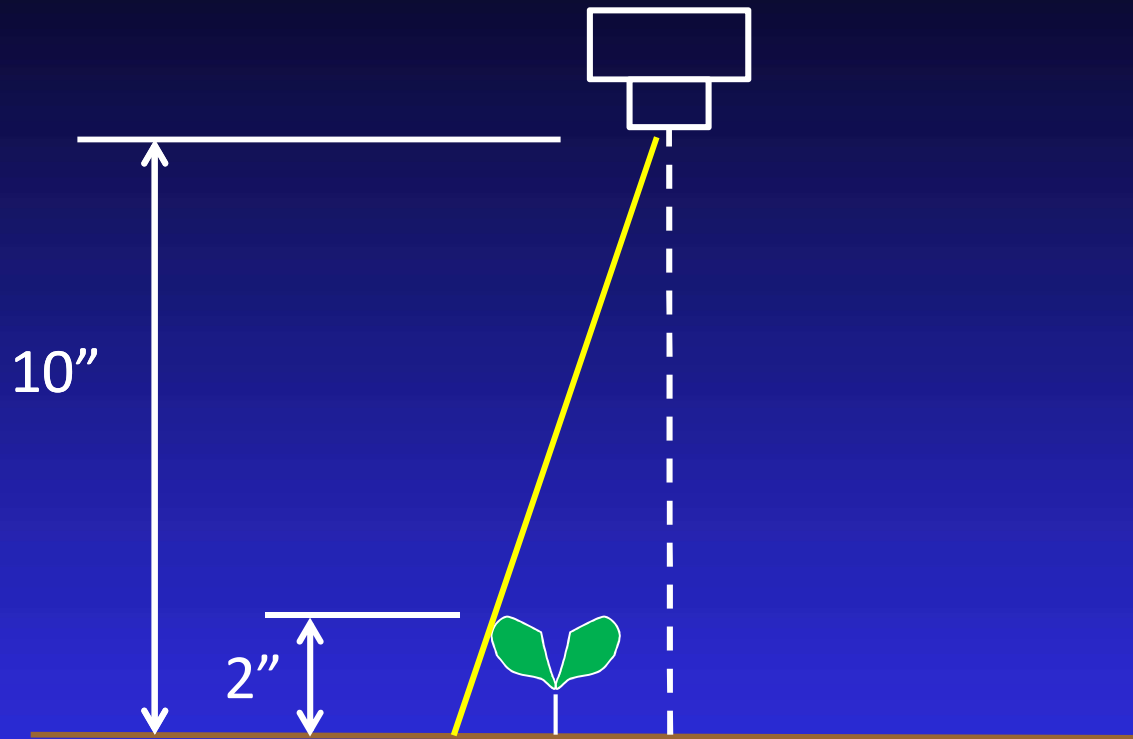


Effect of toolbar rotation:

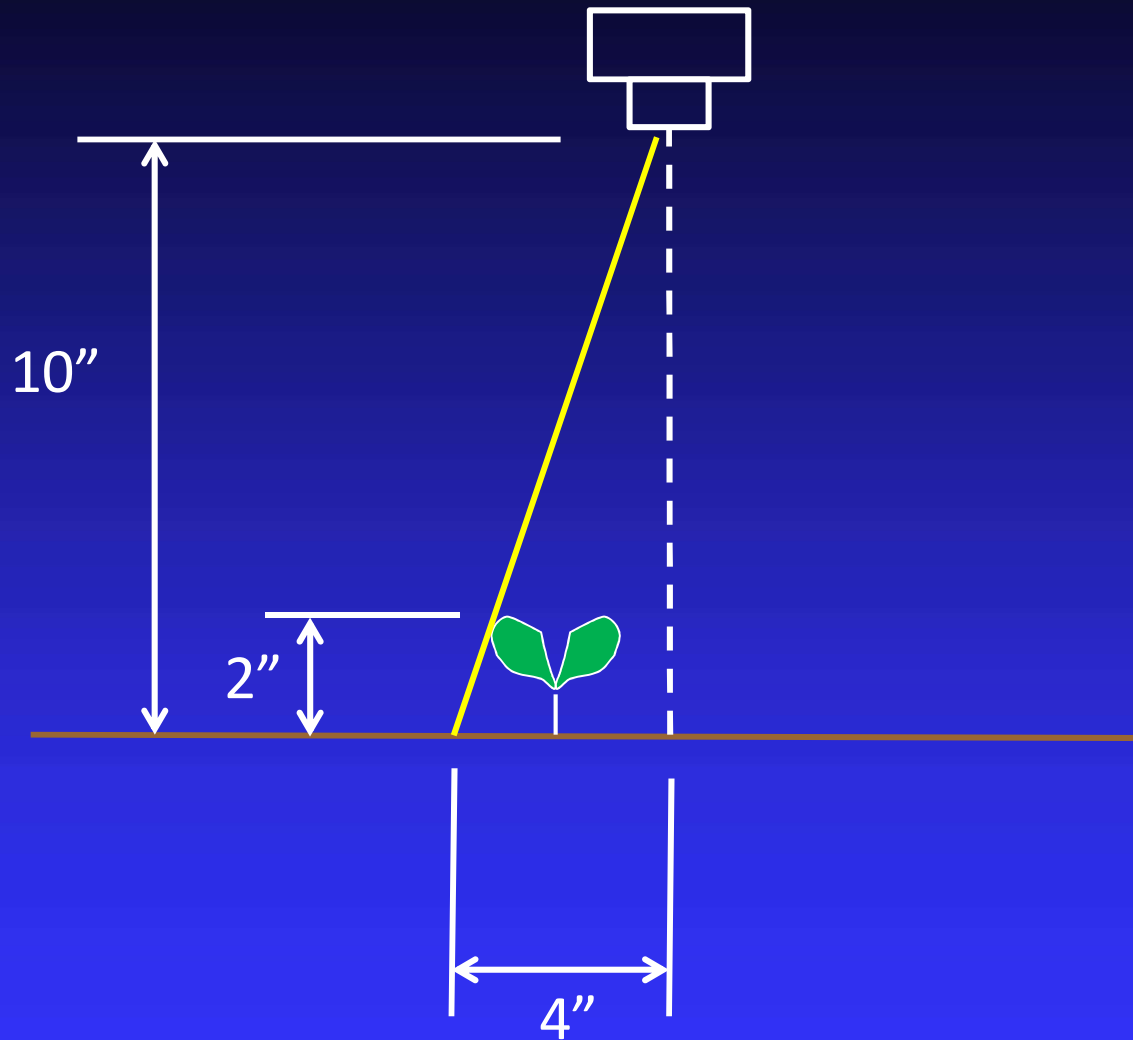
- Camera height – 10"
- Rotation – 1.4°
- Object displacement – 0.25"



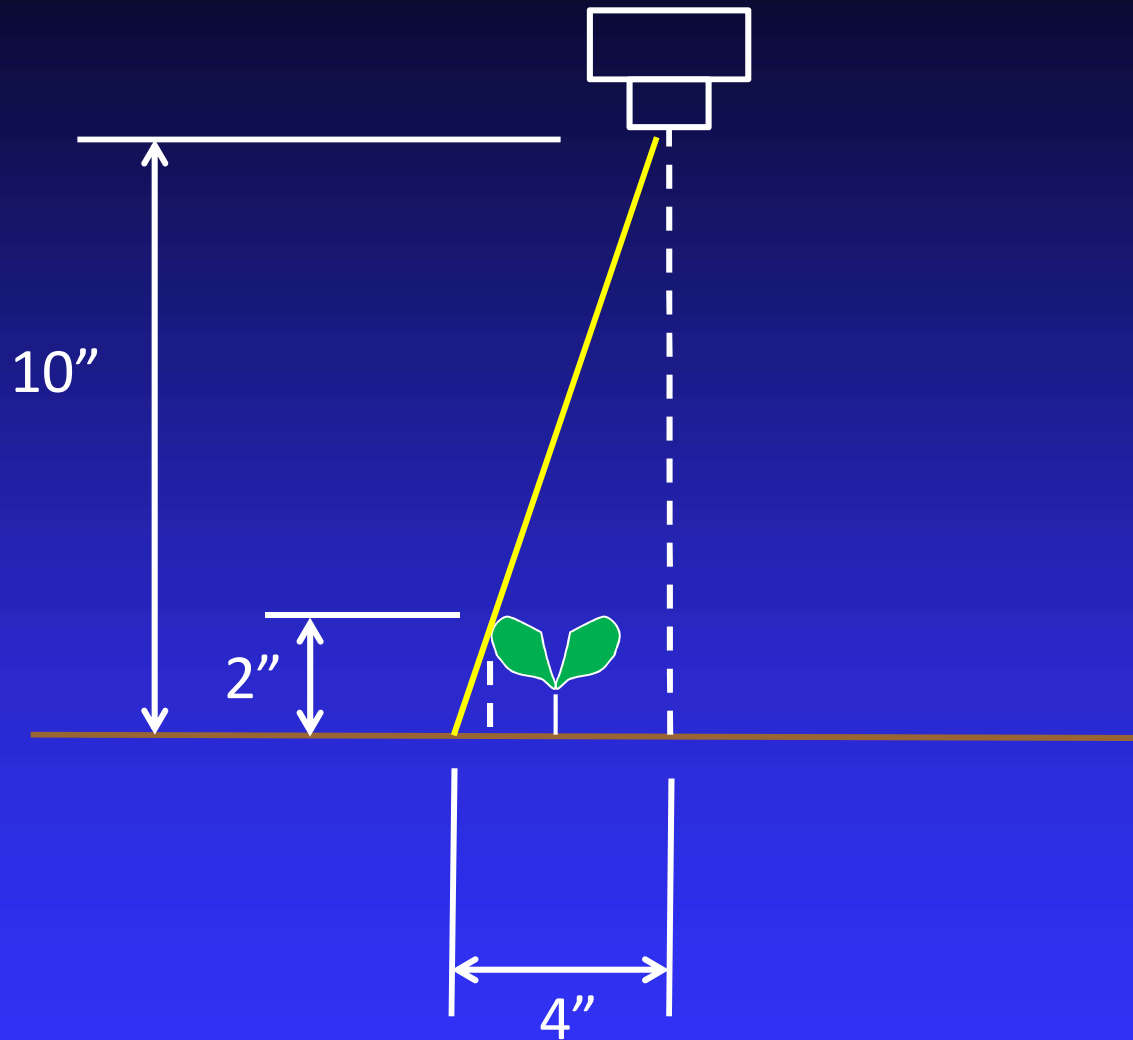
Variable Plant Height



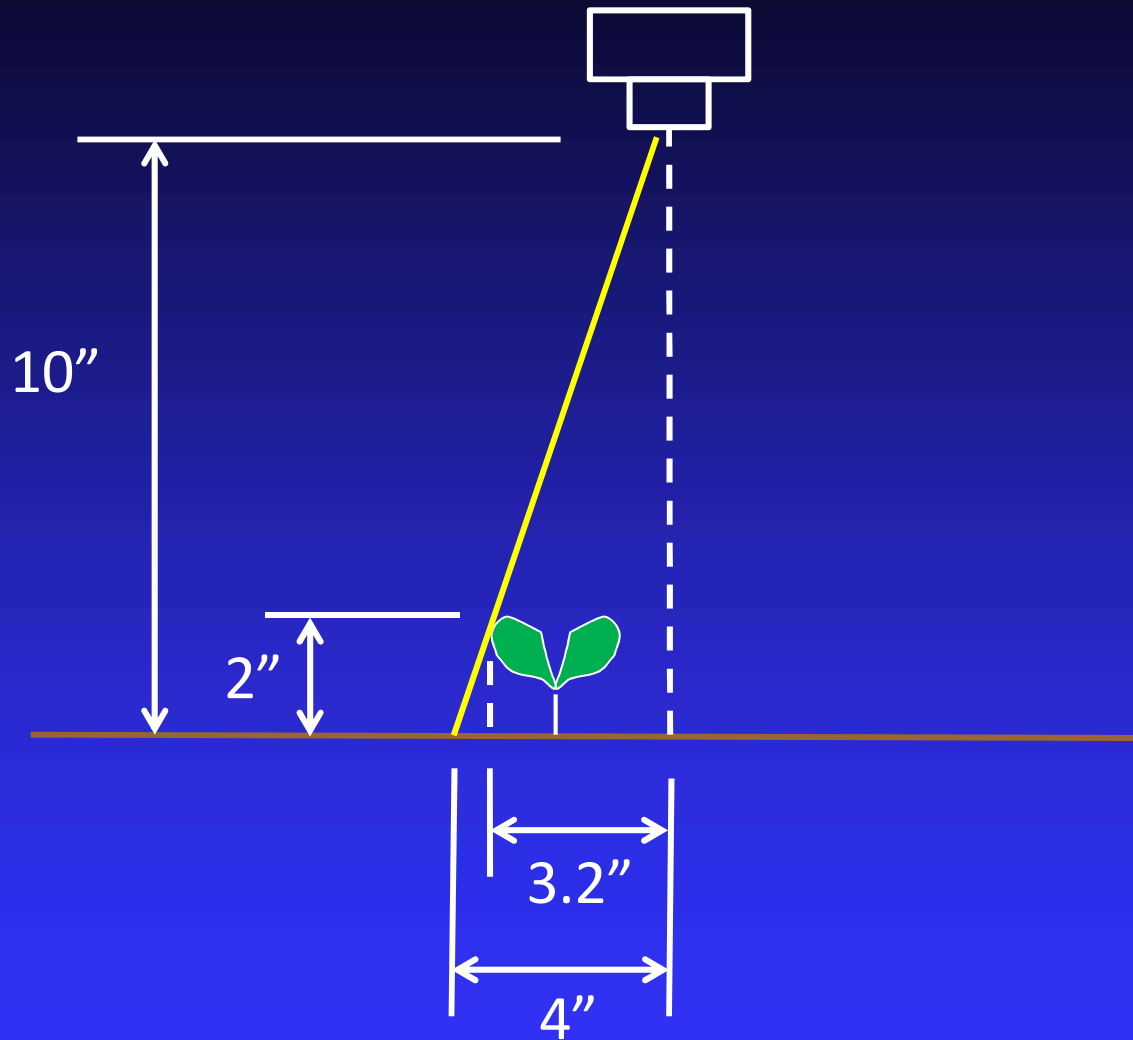
Effect of Plant Height



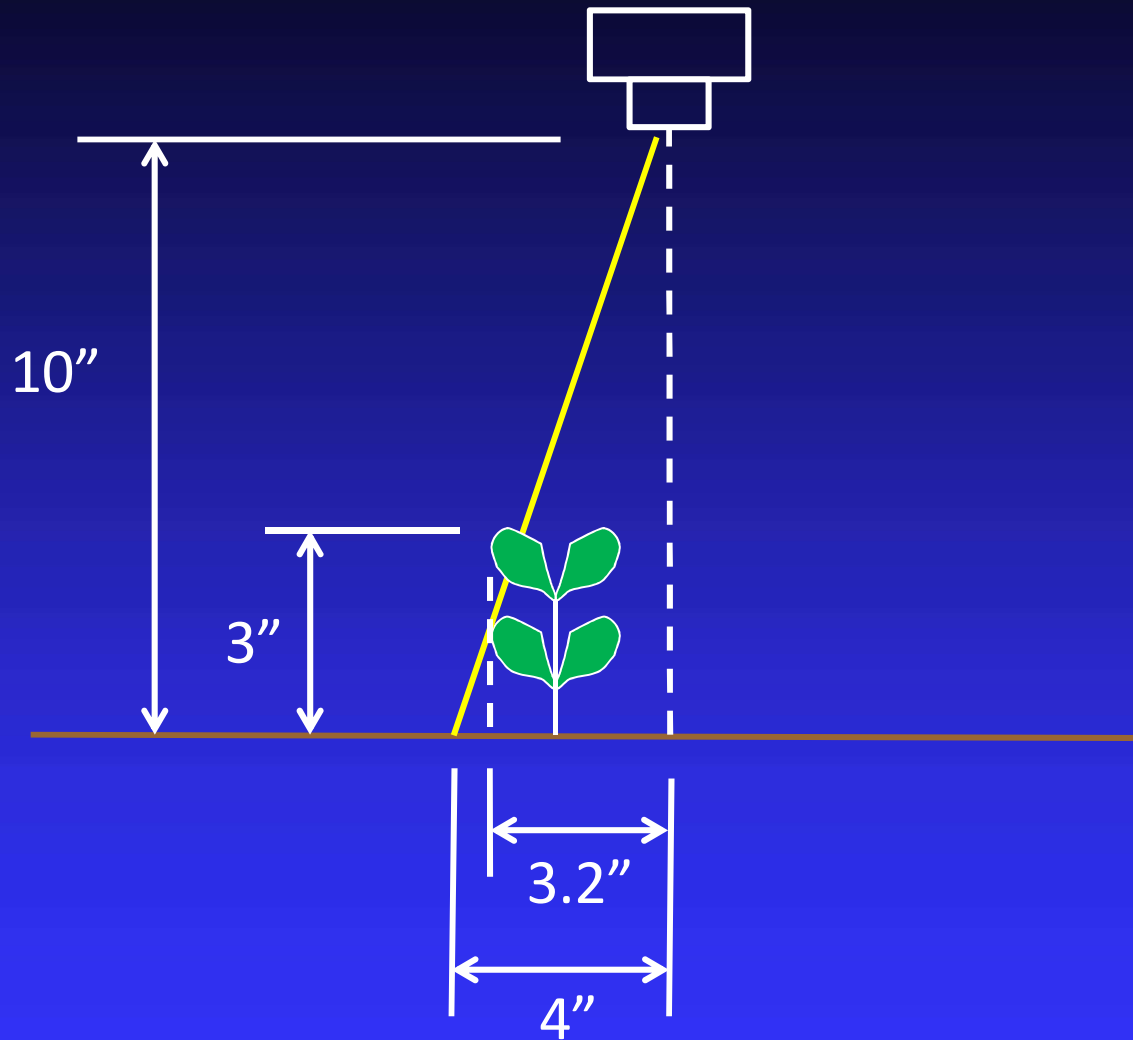
Effect of Plant Height



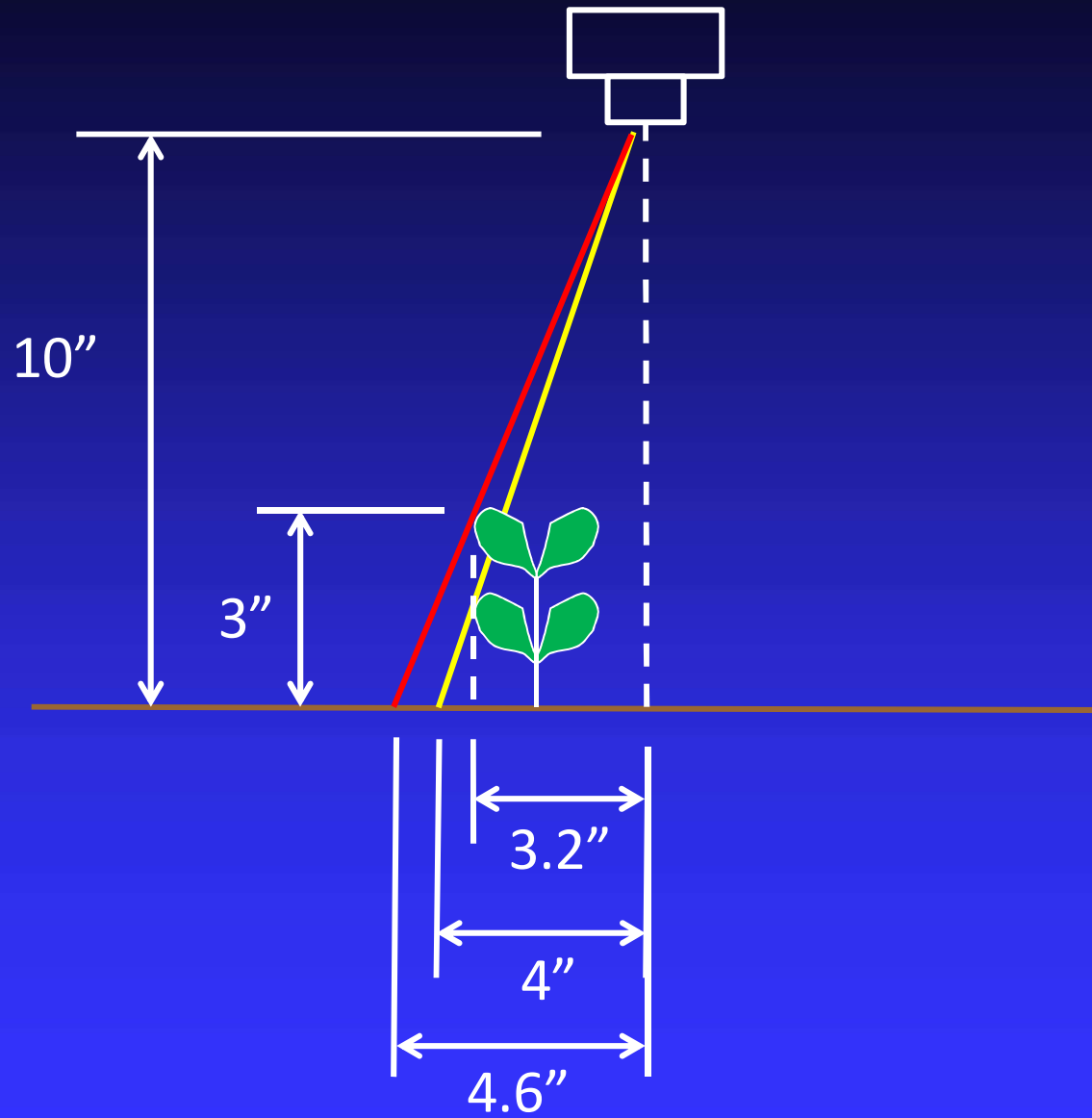
Effect of Plant Height



Effect of Plant Height



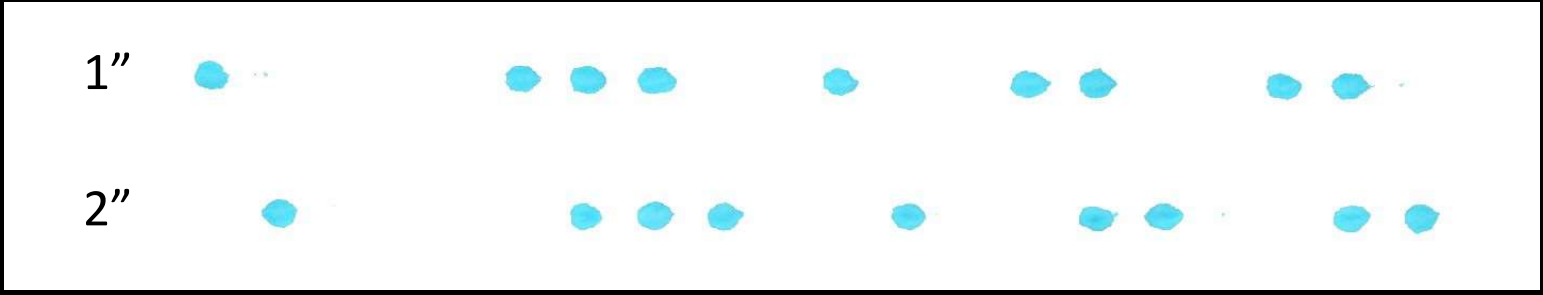
Effect of Plant Height



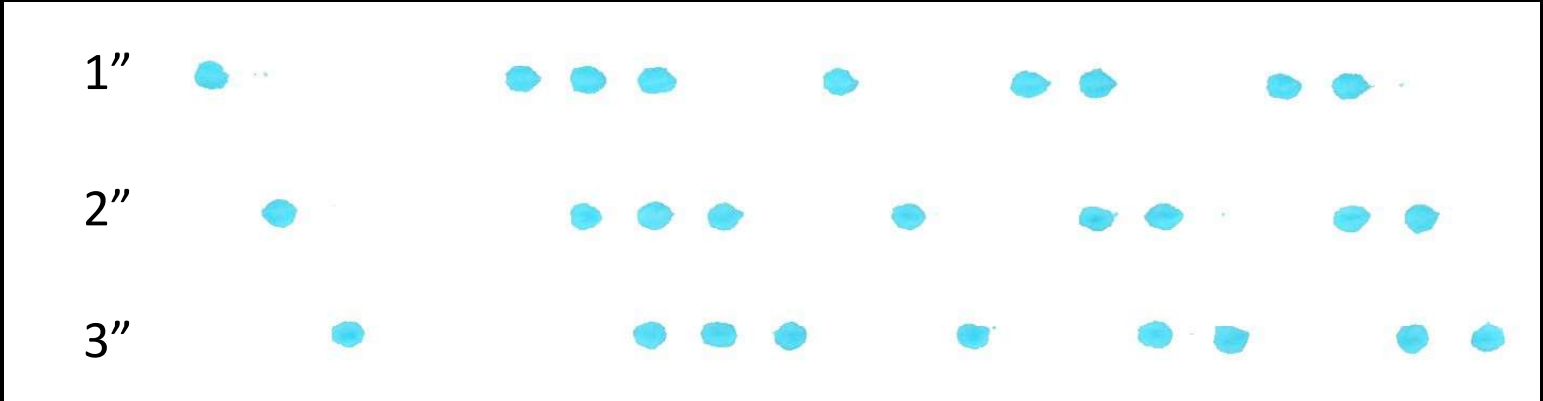
Effect of Plant Height



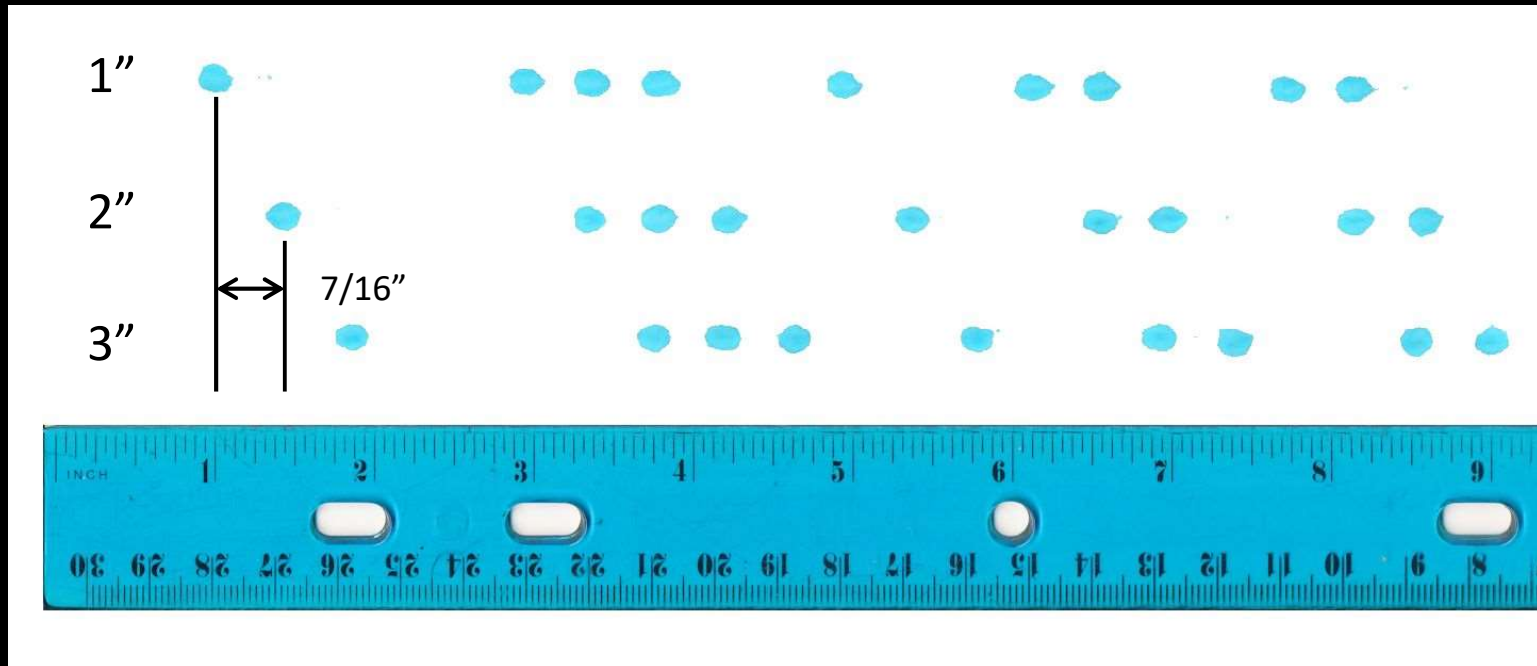
Effect of Target Distance – 2 mph



Effect of Target Distance – 2 mph



Effect of Target Distance – 2 mph



Effect of Target Distance – 2 mph



Precision – 1 cm:

- Self leveling platforms?
- Pivoting sprayers?
- Slow travel speed?



Height Sensing:

- Sonar sensors?
- Range finders?
- 3-D cameras?

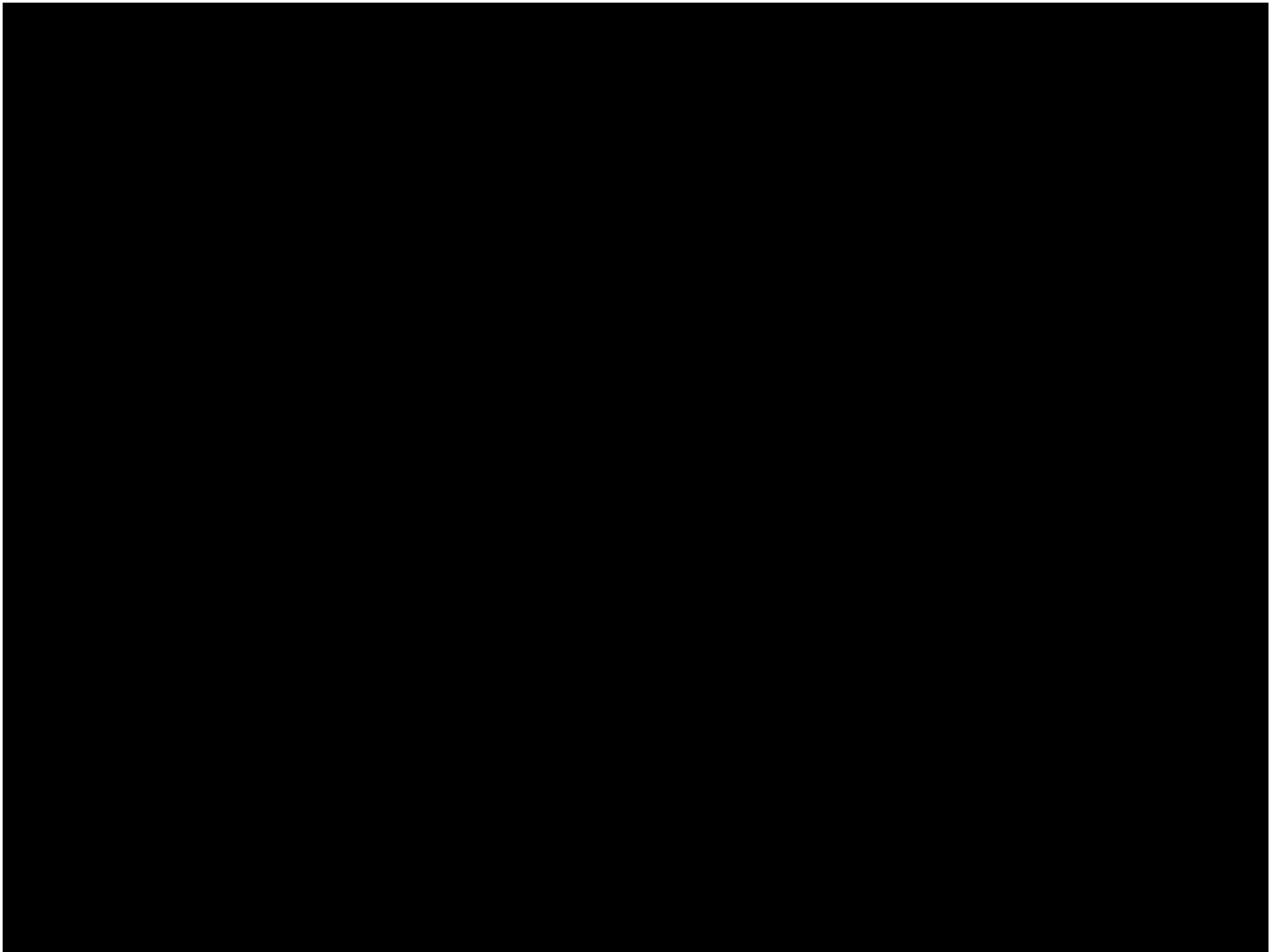


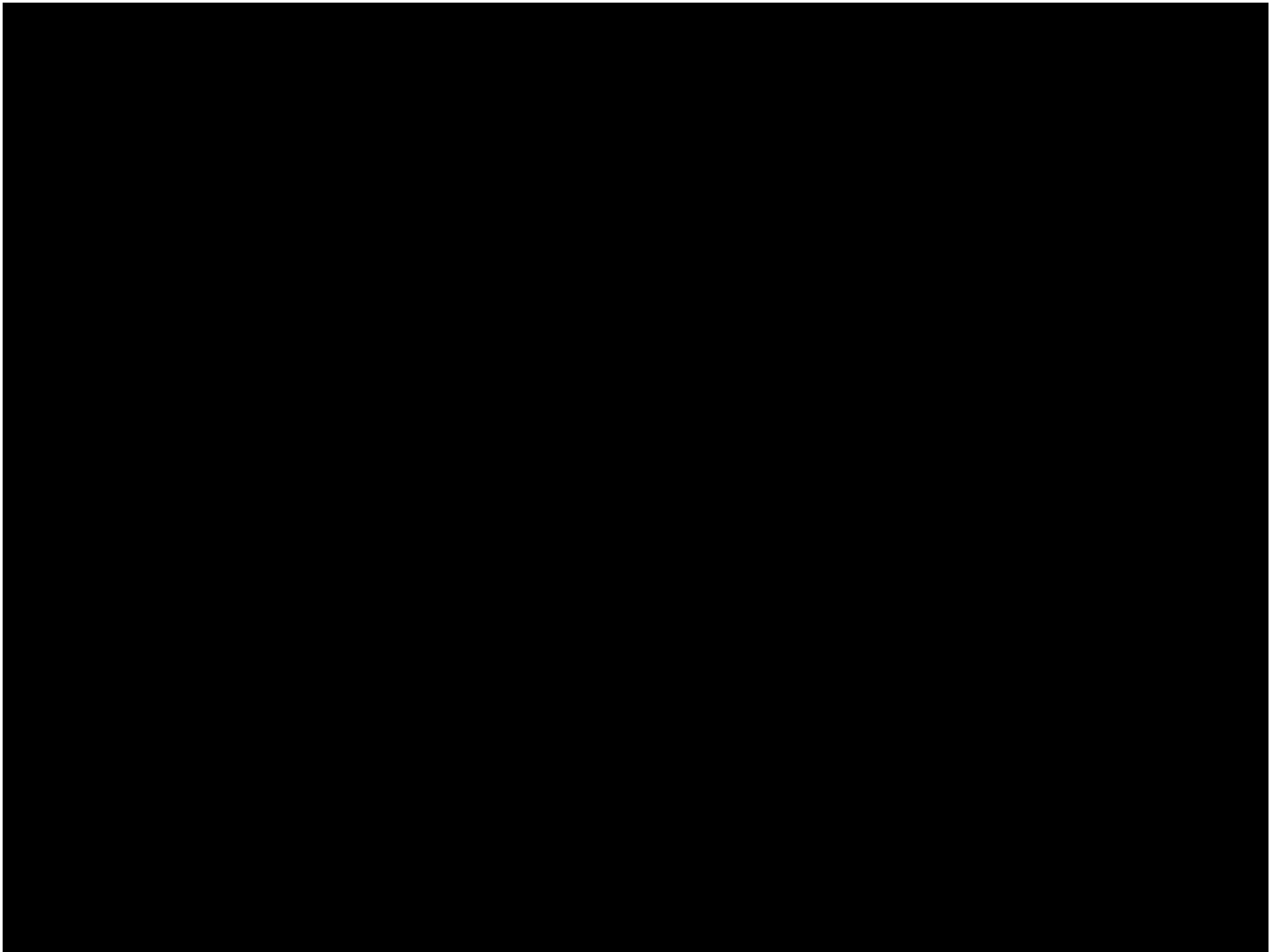
Deepfield Robotics - Bosch Startup Co. (2015)
Mechanical Precision Weeding Machine

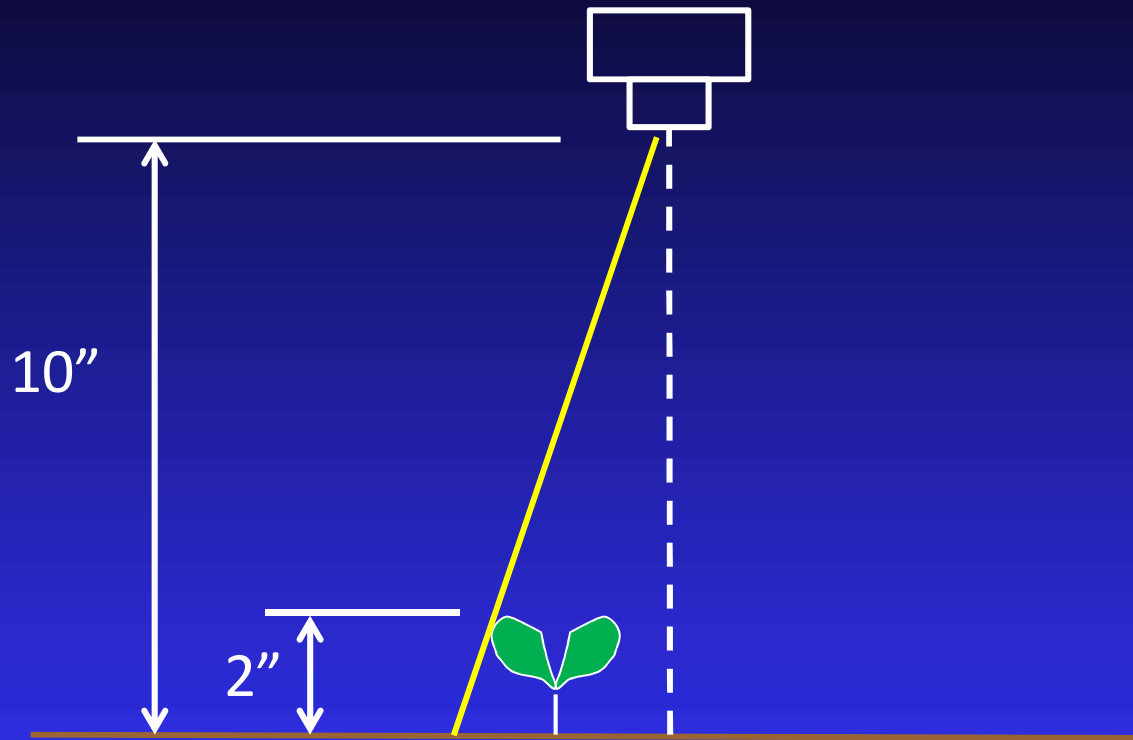
Deepfield Robotics Mechanical Weeder

Thank You

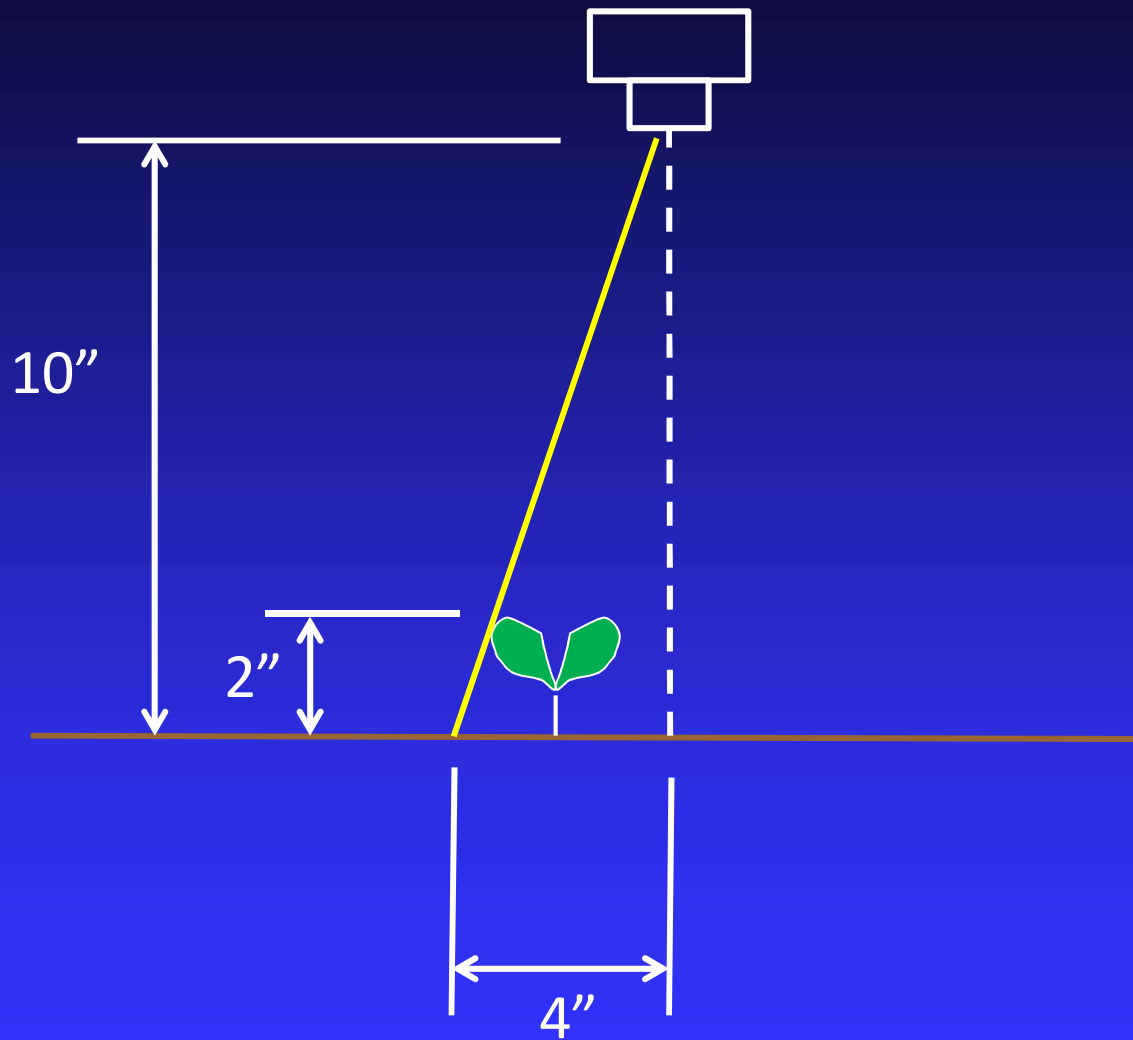




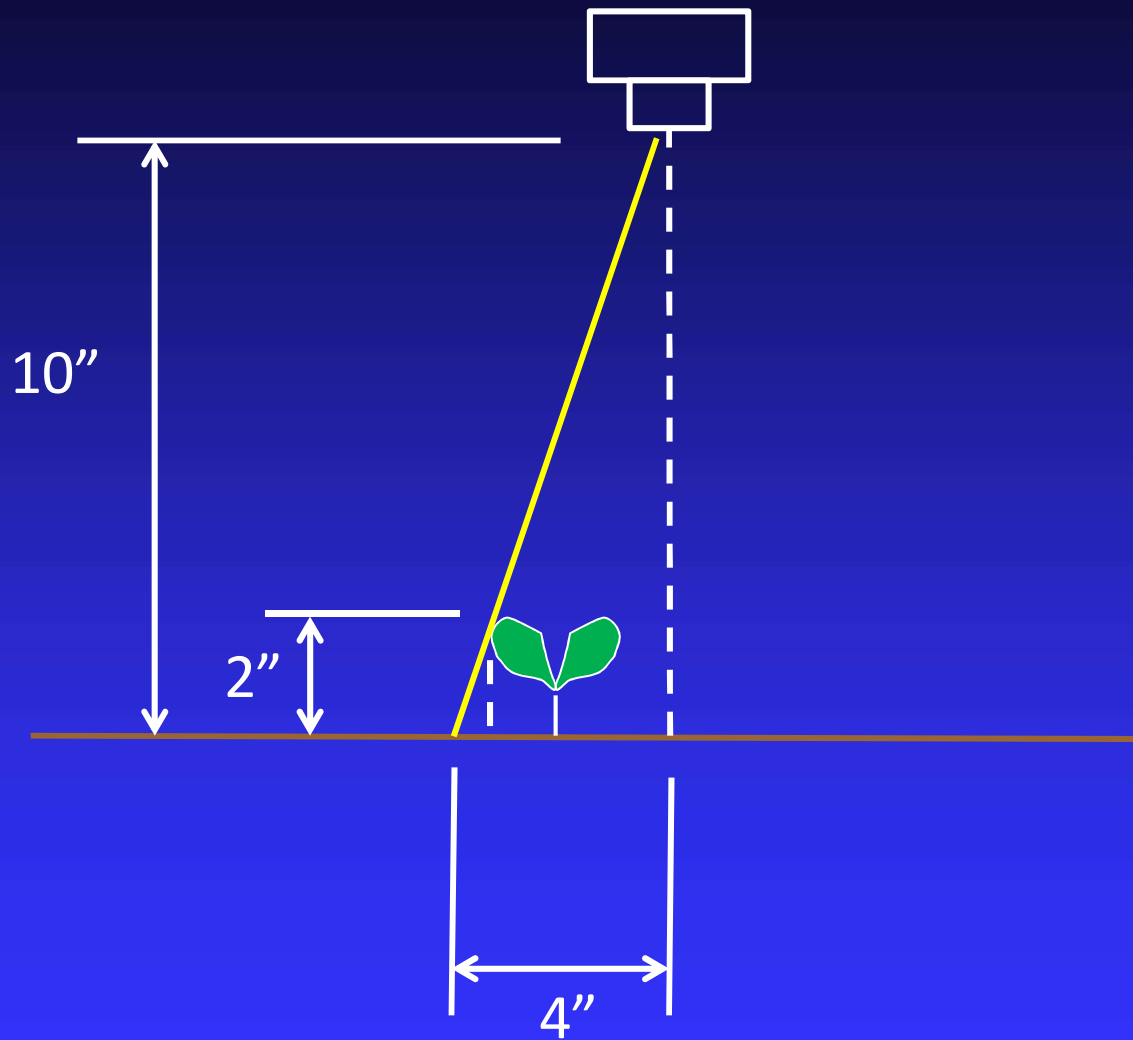




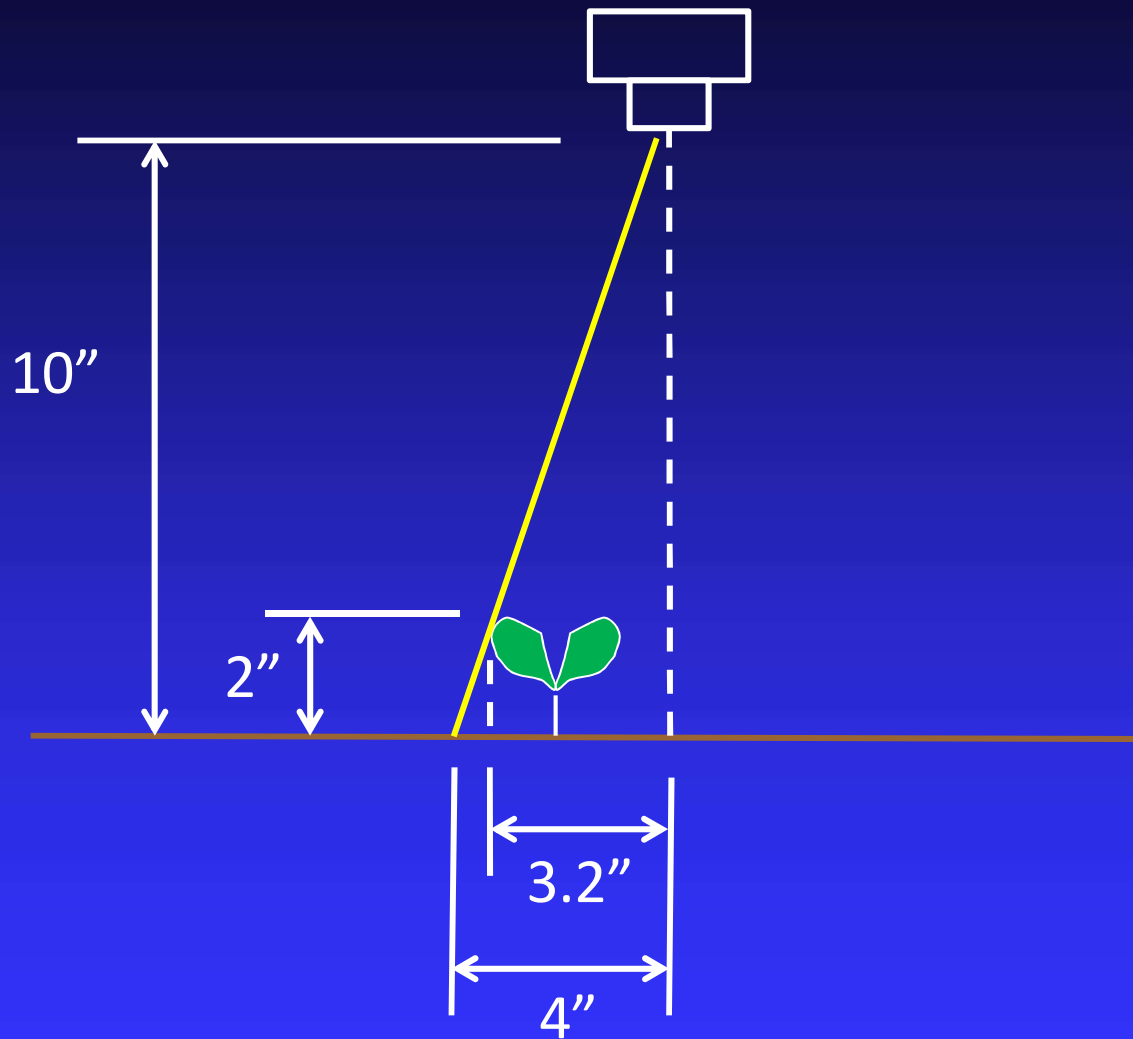
Effect of Plant Height



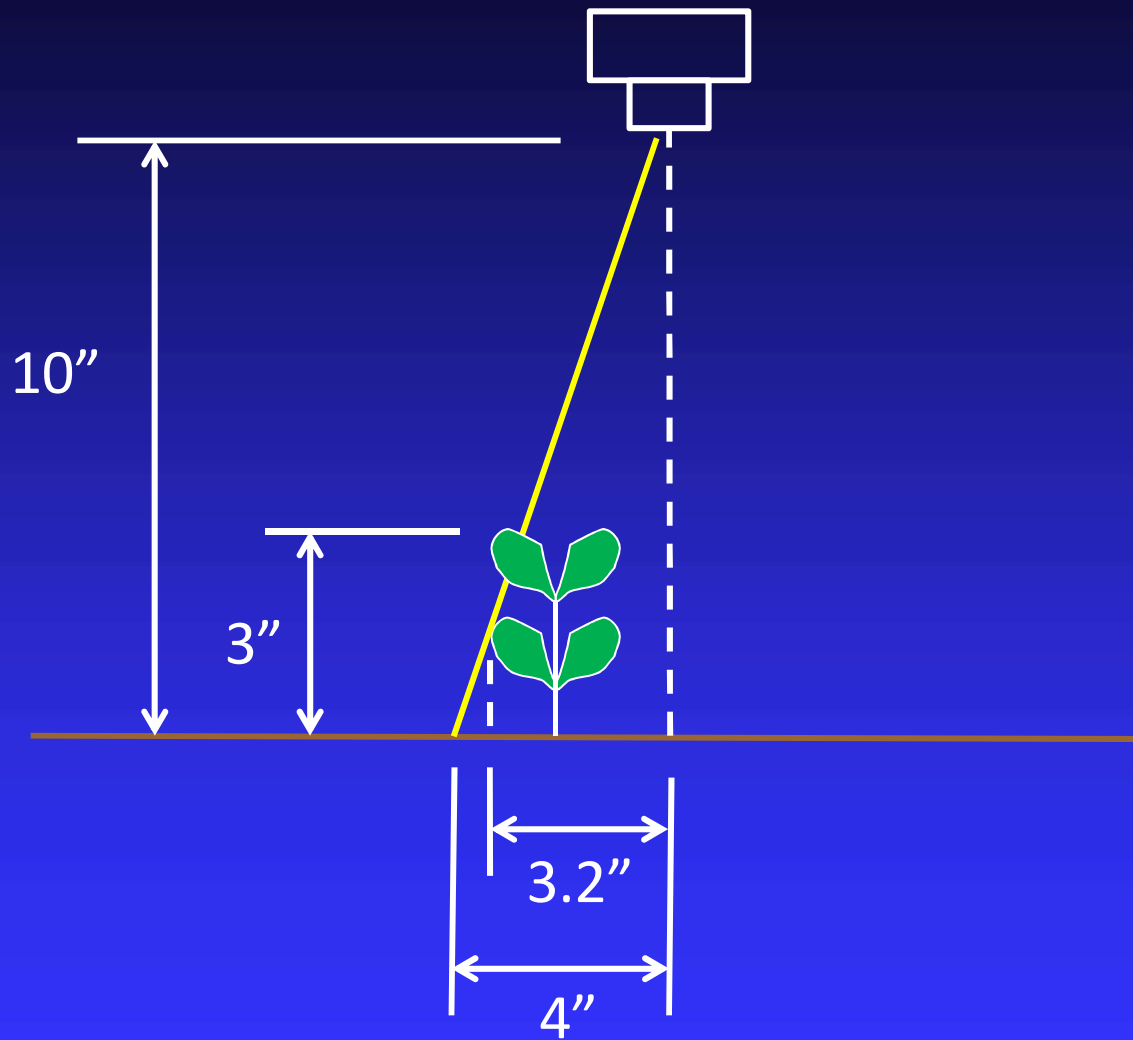
Effect of Plant Height



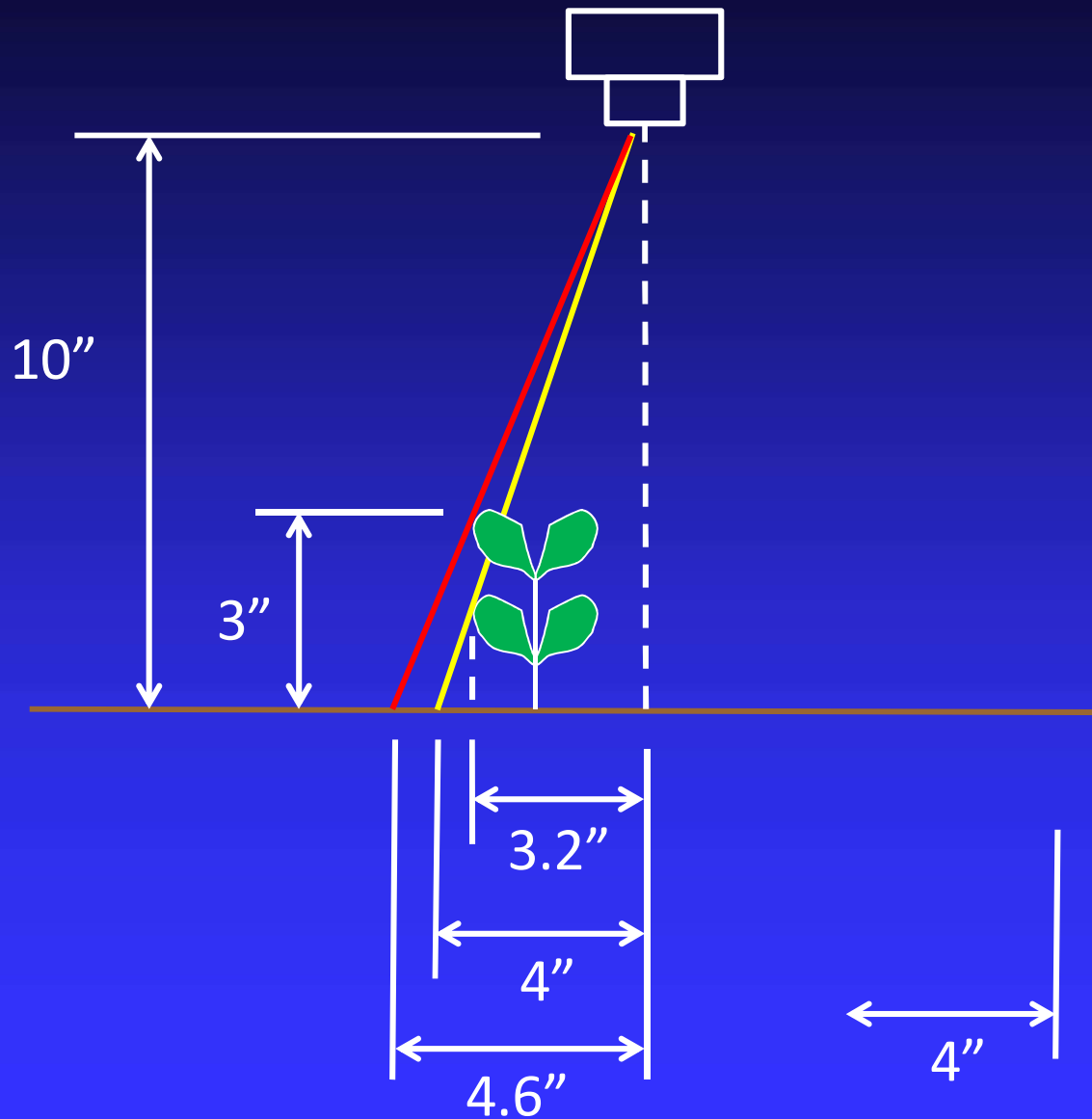
Effect of Plant Height



Effect of Plant Height



Effect of Plant Height



Effect of Plant Height



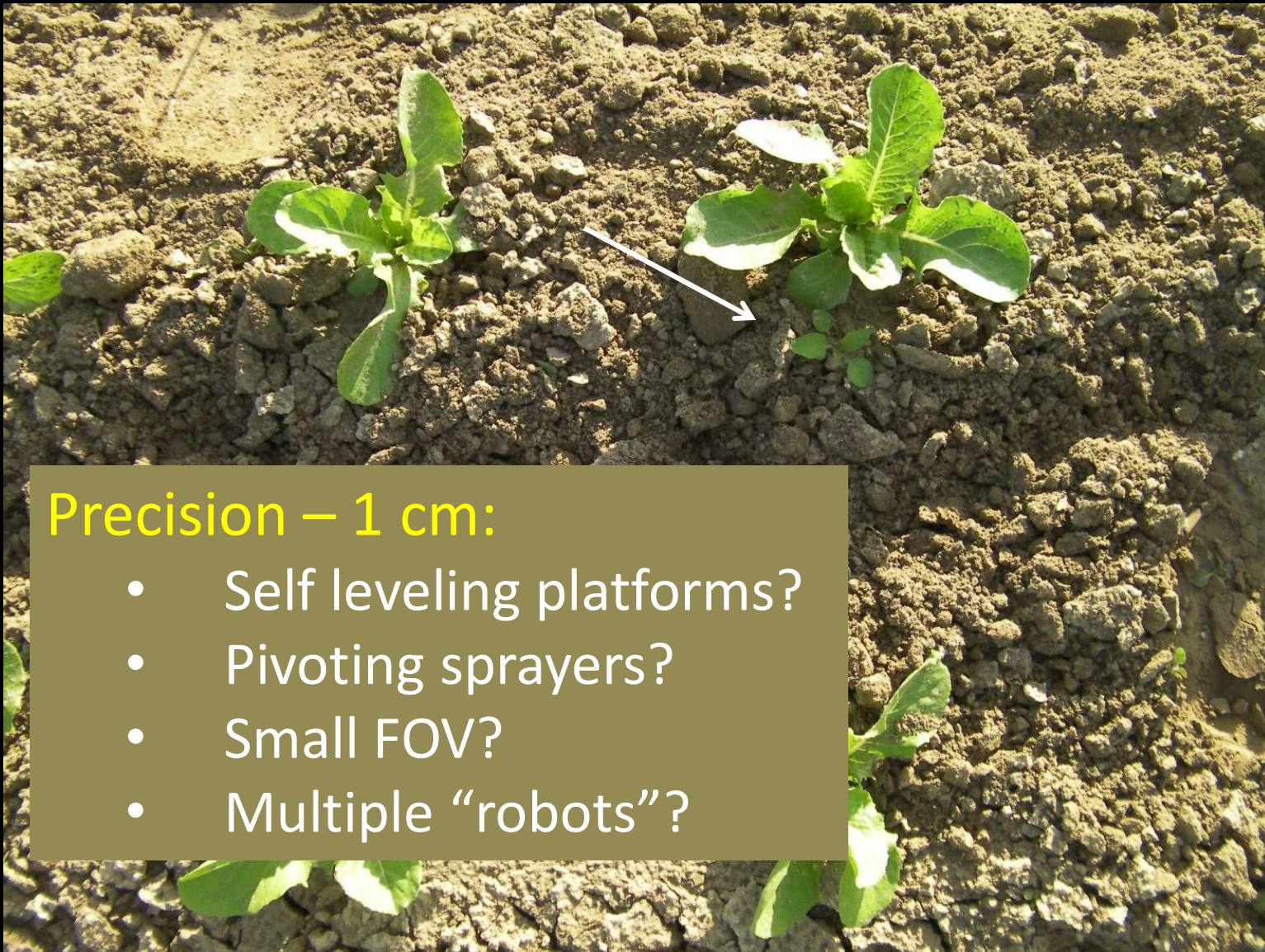
Spray Transplants with Florescent Dye

Specialty Crop Research Initiative Funded Project



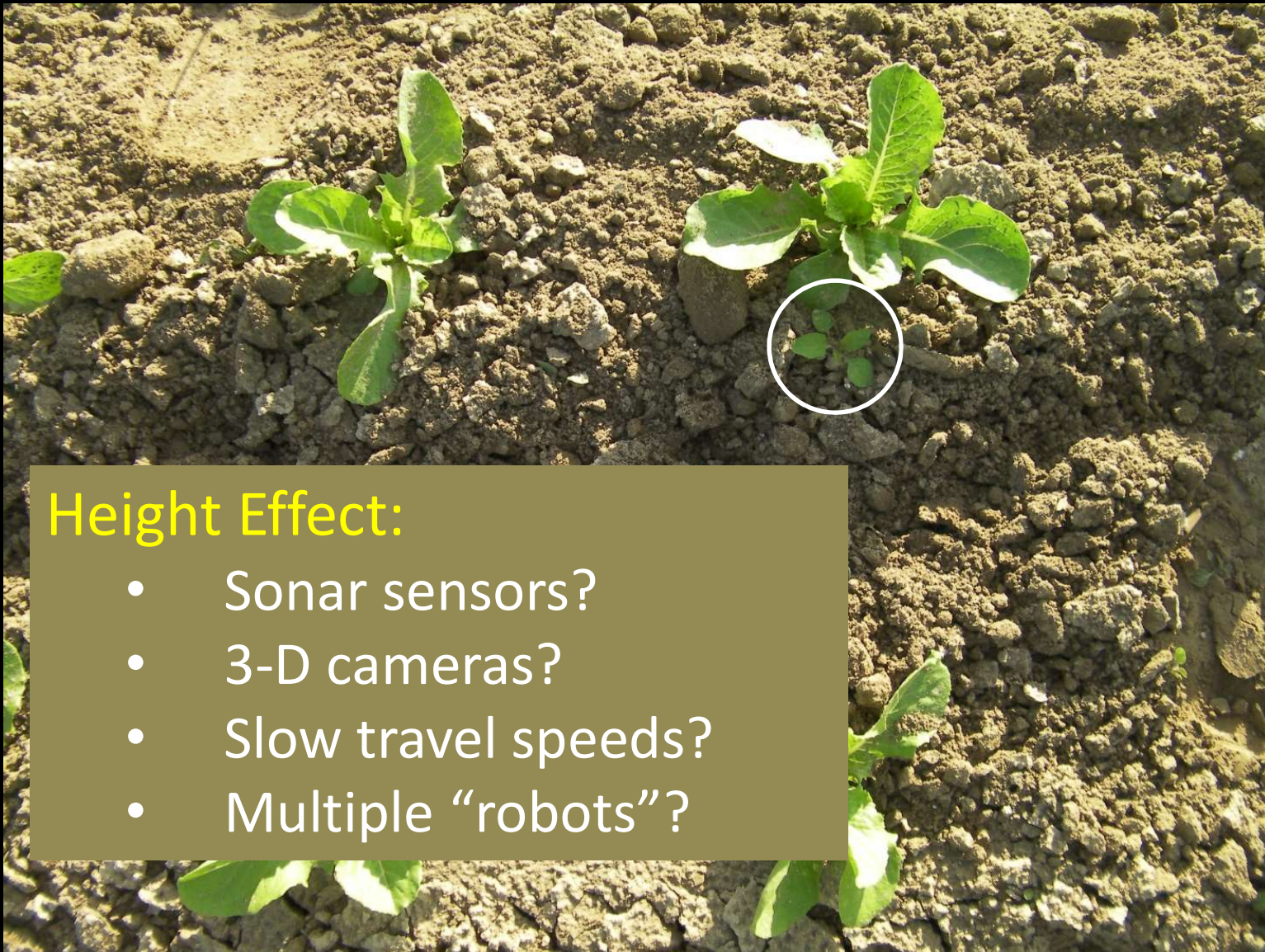
Spray Transplants with Florescent Dye

Specialty Crop Research Initiative Funded Project



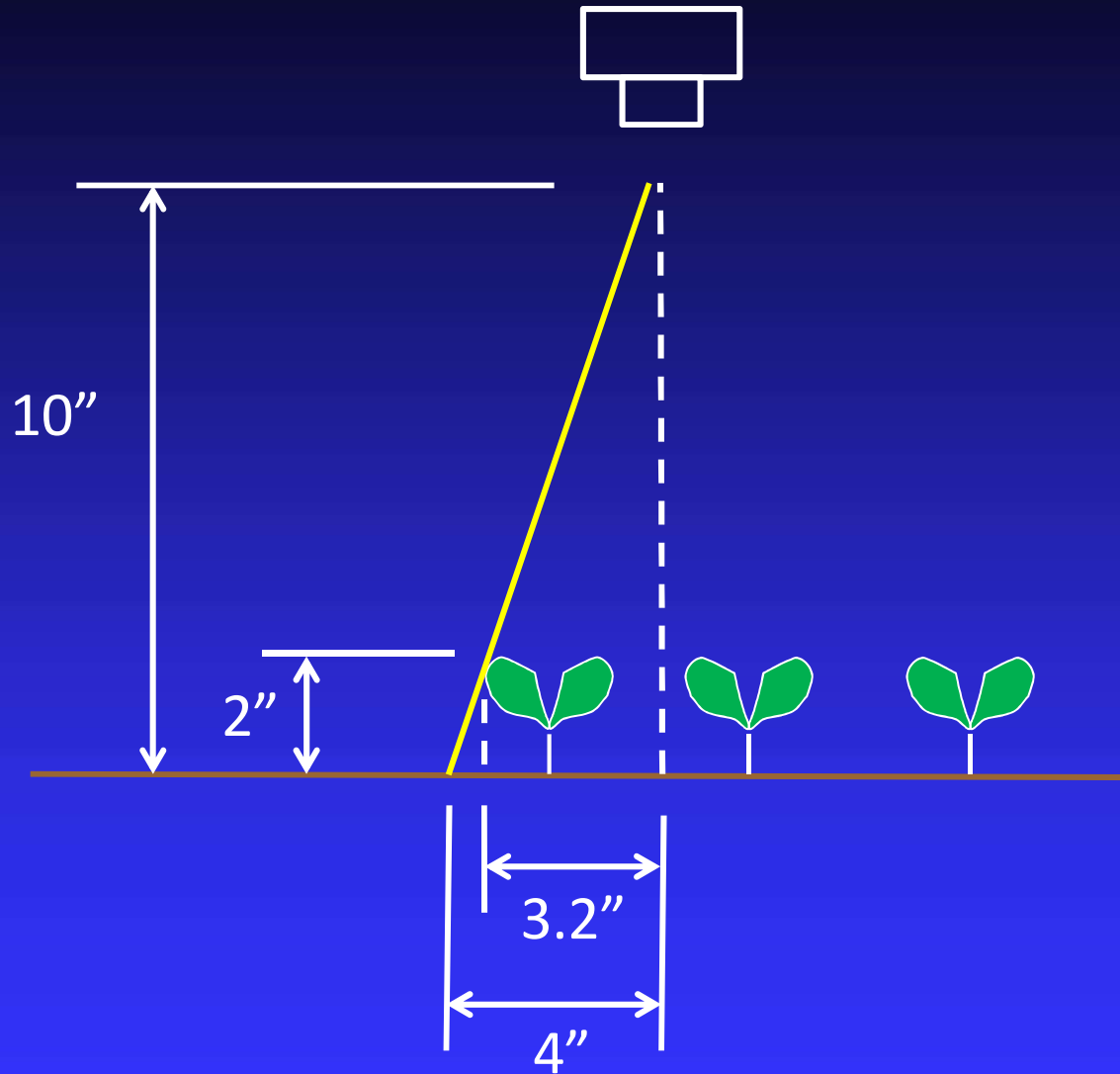
Precision – 1 cm:

- Self leveling platforms?
- Pivoting sprayers?
- Small FOV?
- Multiple “robots”?

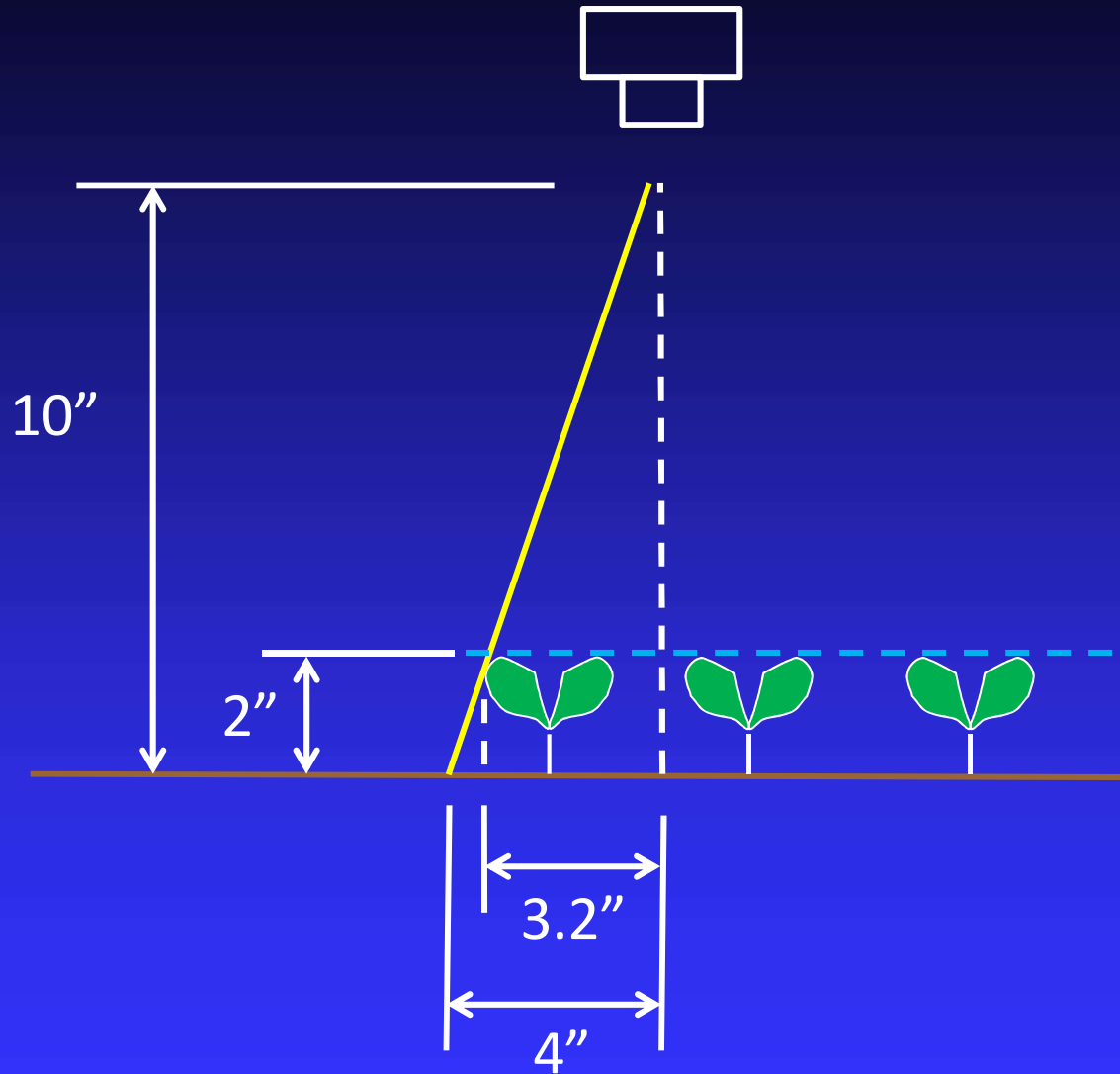


Height Effect:

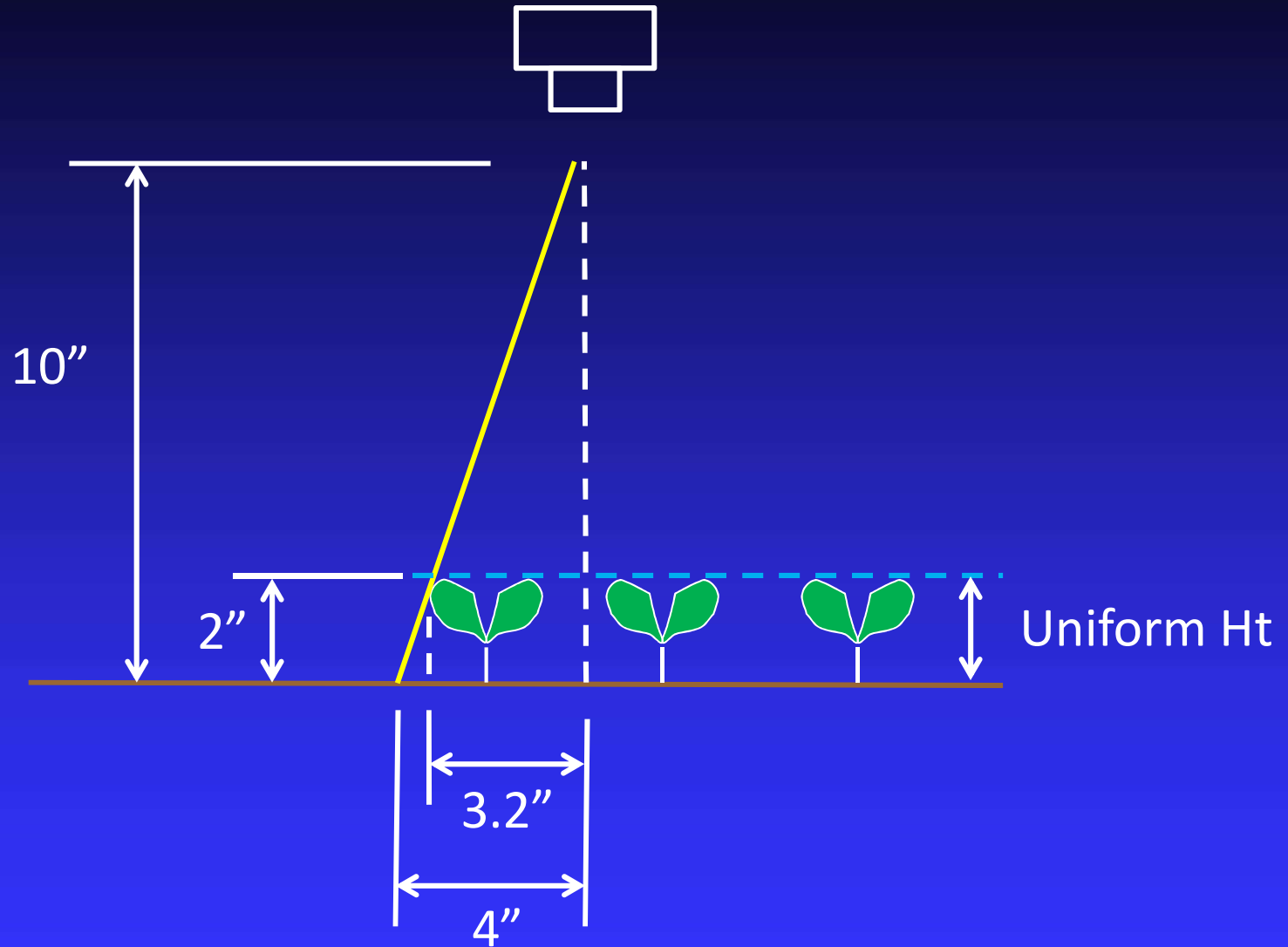
- Sonar sensors?
- 3-D cameras?
- Slow travel speeds?
- Multiple “robots”?



Effect of Plant Height



Effect of Plant Height



Effect of Plant Height



Large Tall Weed



Precision Weeding



Small Clumped Weeds

Summary

- In-row weeders today
 - Remove ~ 2/3rds in-row weeds
- Crop/weed differentiation
 - Deep learning
 - Fluorescent marking
- Precision weeding
 - > 1/2" challenging

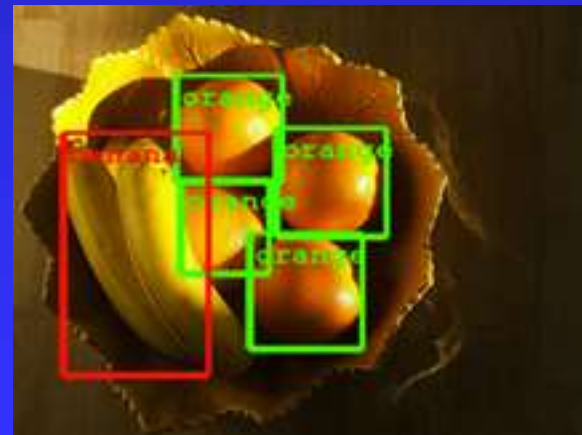
Blue River Technologies Inc.

- + \$17 million (December, 2015)
- Spray based precision weeder
- Crops – Cotton, lettuce, others later
- Deep Learning



Deep Learning

- Training set – millions of images
- Convolutional neural network
- Develops classification algorithm
- ImageNet Contest - <1% error





Precise weeding:

- Self leveling platforms ?
- Pivoting sprayers?
- Slow travel speeds?
- Multiple “robots”?

Thank You



Thank You



Thank You



Thank You

Thank You

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- USDA-NIFA SCRI Grant Program
- USDA-NIFA CPPM Grant Program
- Dr. David Slaughter
- Dr. Steve Fennimore
- Dr. Ran Lati
- Mr. Ron Gayler
- Dr. Mazin Saber
- Mr. Victor Godinez, Jr.
- Dr. David Lyons



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Solution?



Deep Learning

Blue River Technologies Inc.

- + \$17 million (December, 2015)
- Spray based precision thinner/weeder
- Demo- Winter 2016
- Sell Units – Spring 2017



Features

- Self leveling
- Constant height
- Side shift – 4" left or right
- Soil throw on plants
- Limited/no visibility
- ~ 2.5 mph
- \$110,000 for 5 row

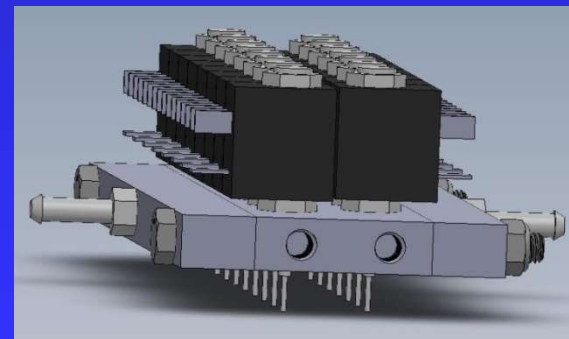
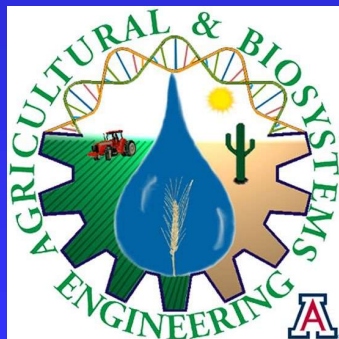


Stekettee IC

Distributor – Sutton Ag Enterprises, Inc., Salinas, CA

Automated Technologies for In-Row Weed Control

Mark C. Siemens
University of Arizona
Department of Ag and Biosystems Engineering



Pre-Season Vegetable Workshop, August 24, 2016

Post Cultivation Hand Weeding Rate

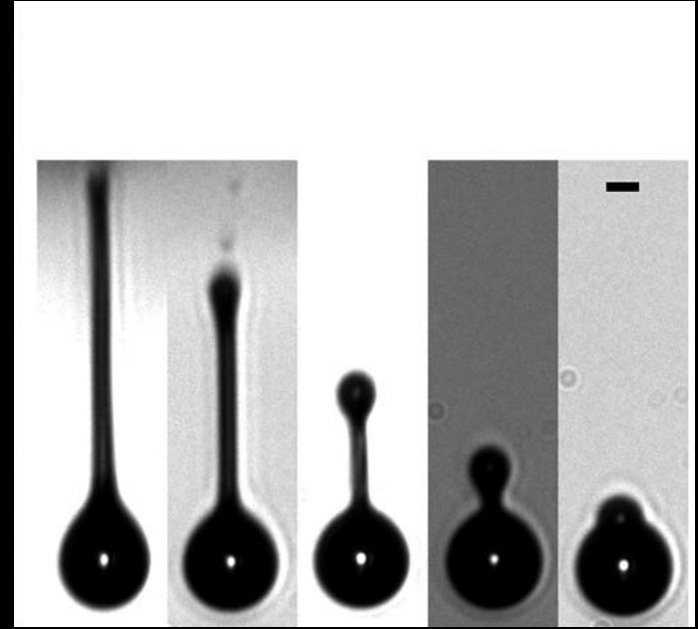
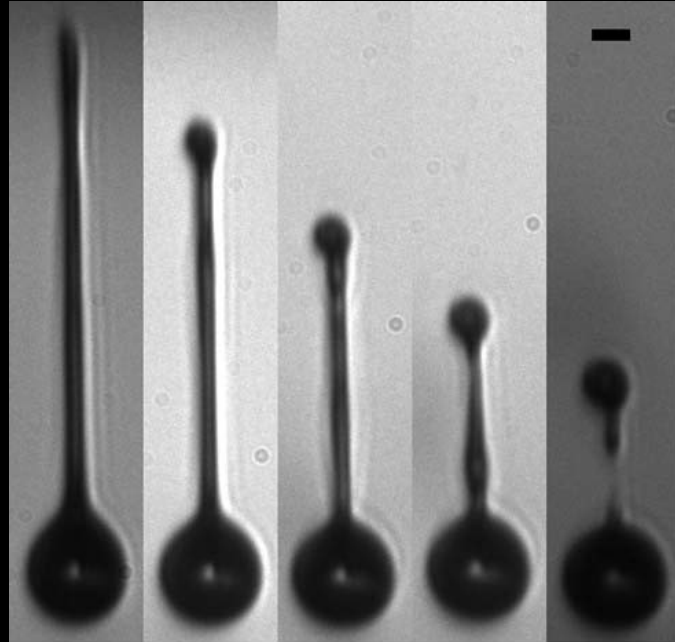
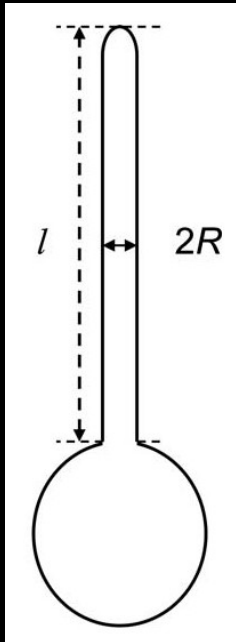
Cult.	Exp. 1	Exp. 2	Exp. 3	Exp. 4	Exp. 5
	-----hr ac ⁻¹ -----				
Conv	35.8 a	12.6 a	10.5 a	23.2 a	10.5 a
Robo	25.3 b	8.4 b	8.4 a	12.6 b	8.4 a
Diff.	10.5	4.2	NS	10.5	NS

Post Cultivation Hand Weeding Rate

Cult.	Exp. 1	Exp. 2	Exp. 3	Exp. 4	Exp. 5
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Conv	35.8 a*	12.6 a	10.5 a	23.2 a	10.5 a
Robo	25.3 b	8.4 b	8.4 a	12.6 b	8.4 a
Diff.	10.5	4.2	2.1	10.5	2.1

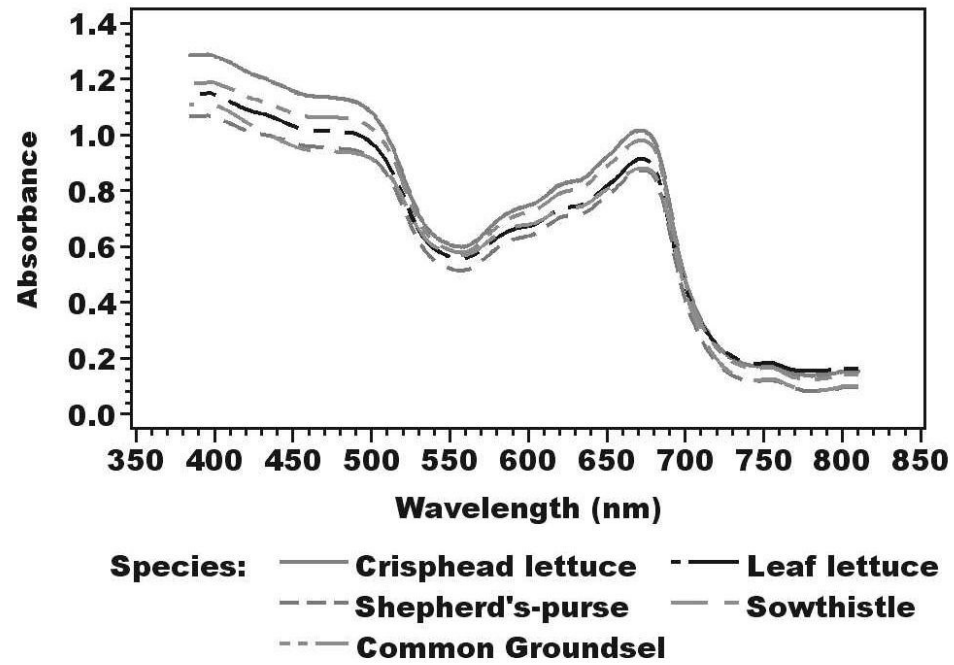
* Difference in means significantly different according to Tukey-Kramer HSD test (P=0.05)

Technically Challenging

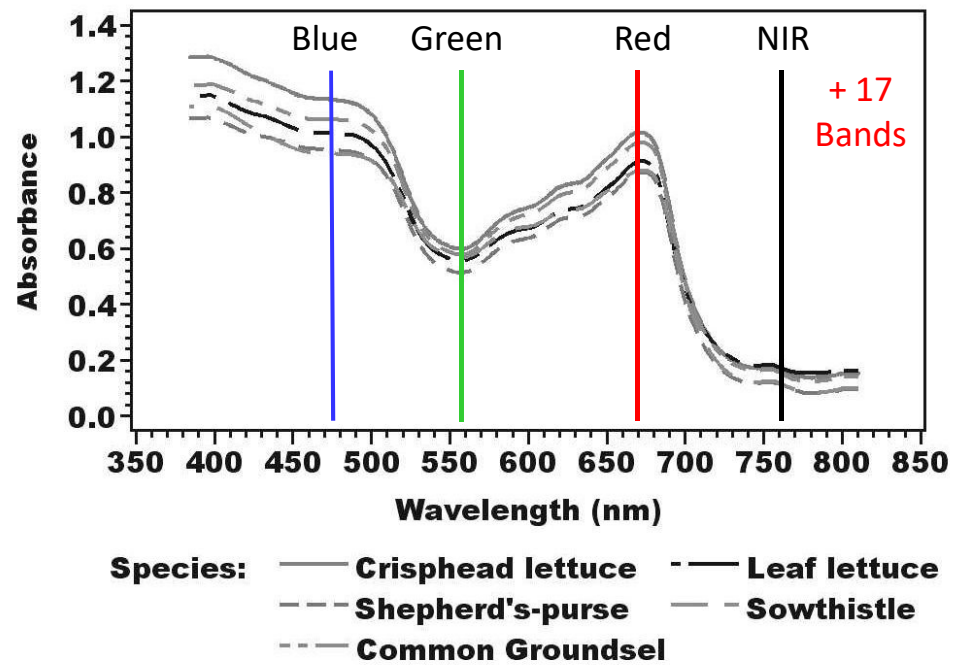


Droplet Stability

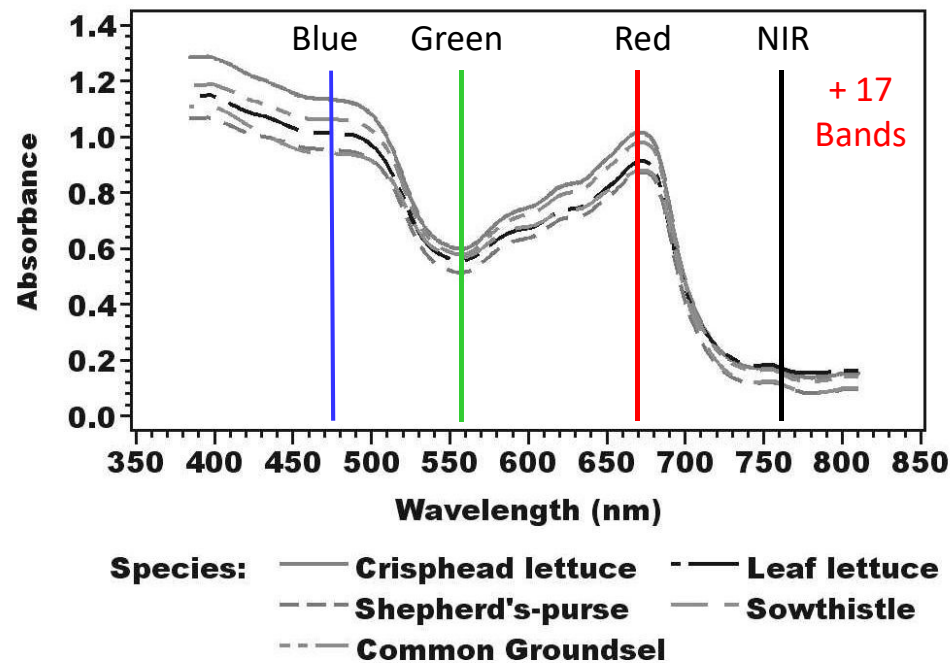
- Filament length (l)
- Filament radius (R)
- Droplet diameter
- Velocity
- Density
- Viscosity
- Surface tension



Slaughter et al., 2008



Slaughter et al., 2008



Slaughter et al., 2008

Performance of Multispectral Machine Vision System

Plant Species	Classification Accuracy
Head lettuce	89.4%
Groundsel	83.6%
Leaf lettuce	94.0%
Shepherd's-purse	89.4%
Sowthistle	92.5%
All lettuce	91.3%
All weeds	87.8%
Overall average	90.3%



Thin and Spot Spray Marker Dye



Tillet-Hague Weeder

“Robocrop” - Garford Corp., Peterborough, EN

Limited Adoption in U.S.

- Transplanted crops - adequate
 - Yield, net returns similar
- Direct seeded crops – not recommended
 - Stand decreased
 - Yield and net returns lower

Fennimore et al. (2014)

Robotic In-Row Weeders

- Commercialized – 2008
- Developed in Europe
 - High labor costs
 - Transplanted crops
- Mechanical
 - Oscillating and rotating blades

Blue River Technologies Inc.

- + \$17 million (December, 2015)
- Spray based precision weeder





Thank You

